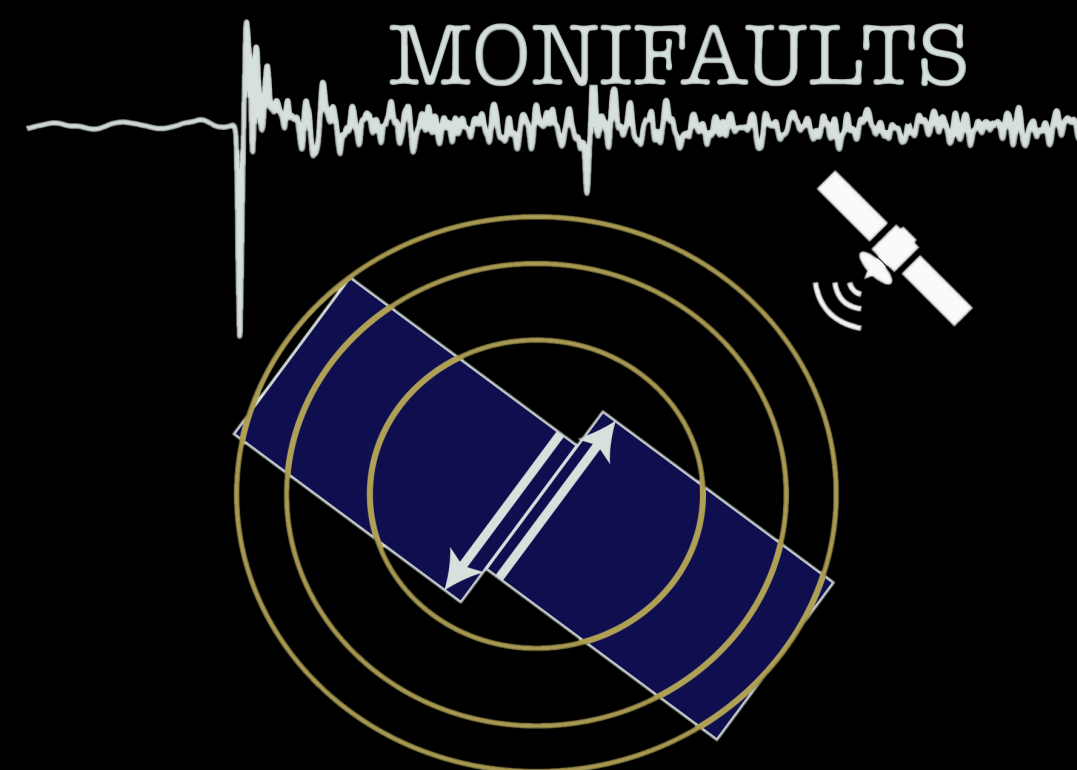


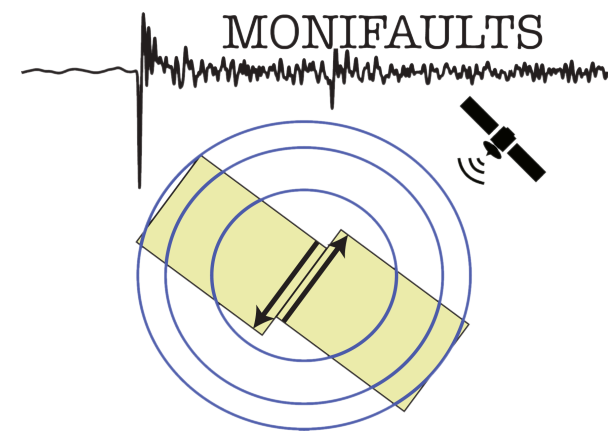
Tackling earthquake detection problem using 1D Convolutional Neural Networks

Josipa Majstorović, Sophie Giffard-Roisin and Piero Poli



UNKNOWN FEATURES



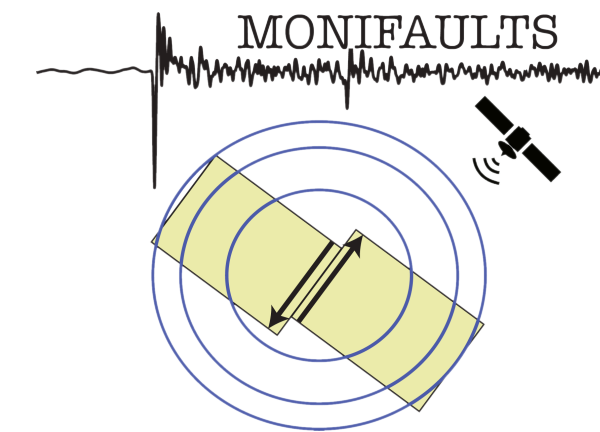


Basics of neural networks, deep learning models

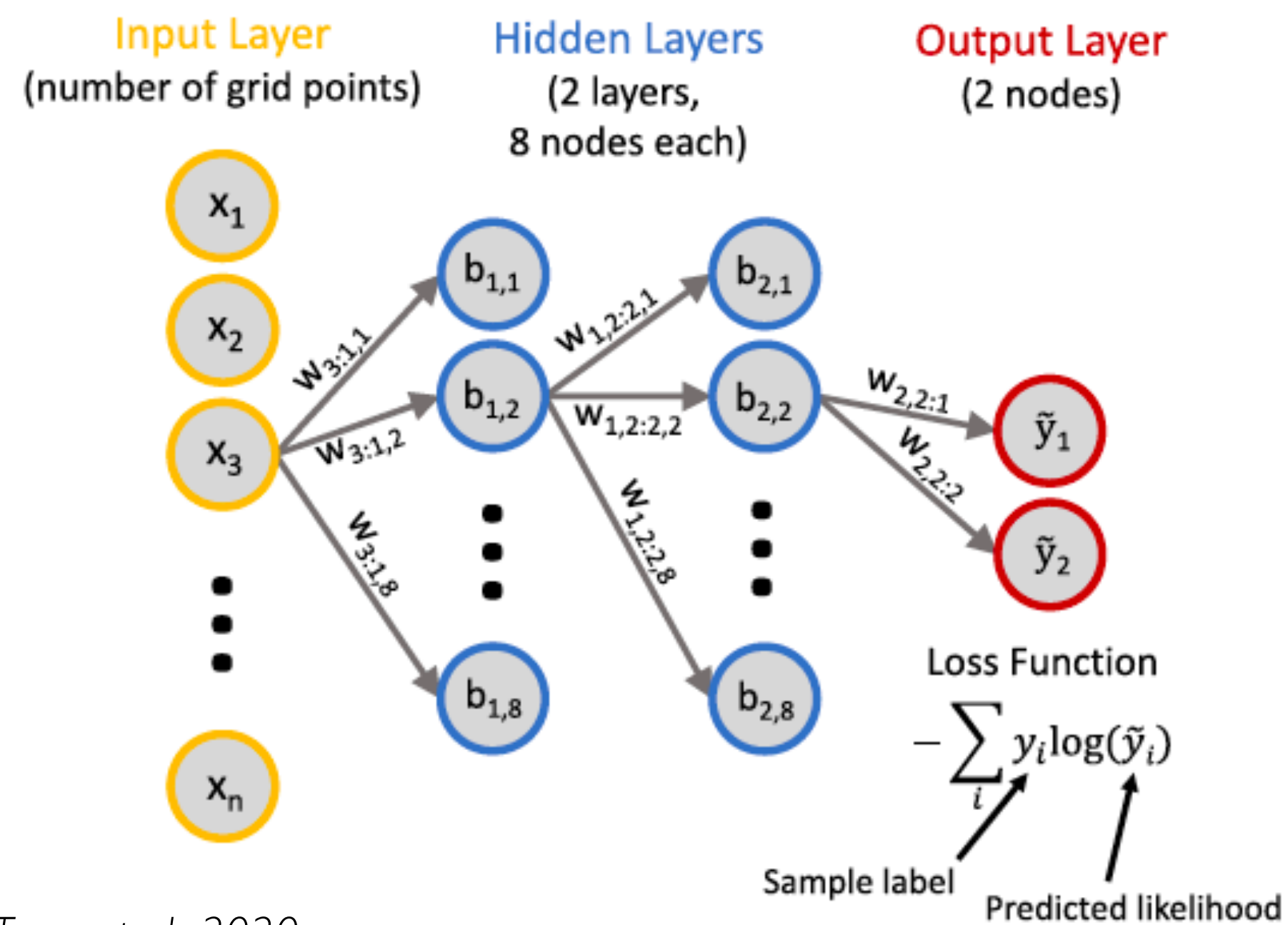
Developing CNN detector

What does interpretation stand for in DL?

Goal: to further understand how we can exploit the existing DL models for the earthquake detection and whether we can find some other application.



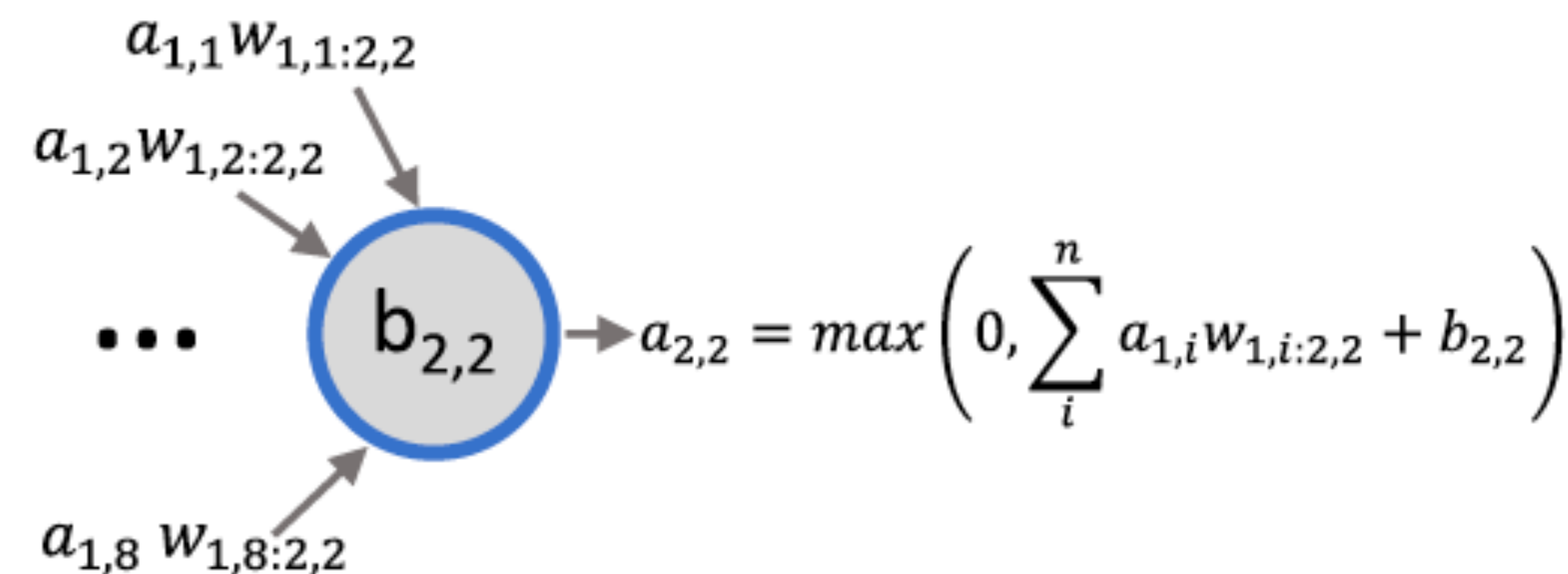
NEURAL NETWORK



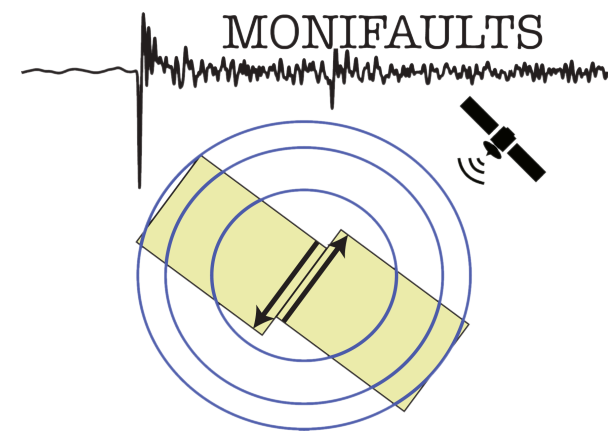
Toms et al., 2020

Deep learning - Collection of neural networks, biologically inspired networks, that extract abstract features from the data in a hierarchical fashion.

BASIC UNIT - NEURON (NODE)



During the training process of the neural network we adjust the **weights and biases**.



The performance of the NN model highly depends on:

1 Training data

Datasets and labels!

2 Training process

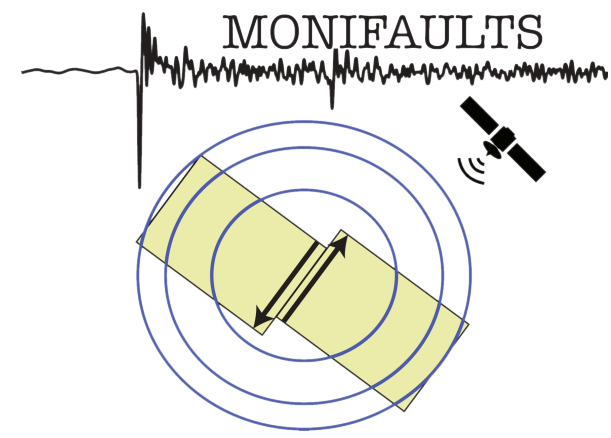
Hyperparameters such as optimising algorithms, learning rates ...

2 Modelling approach

Classification vs regression

3 NN architecture

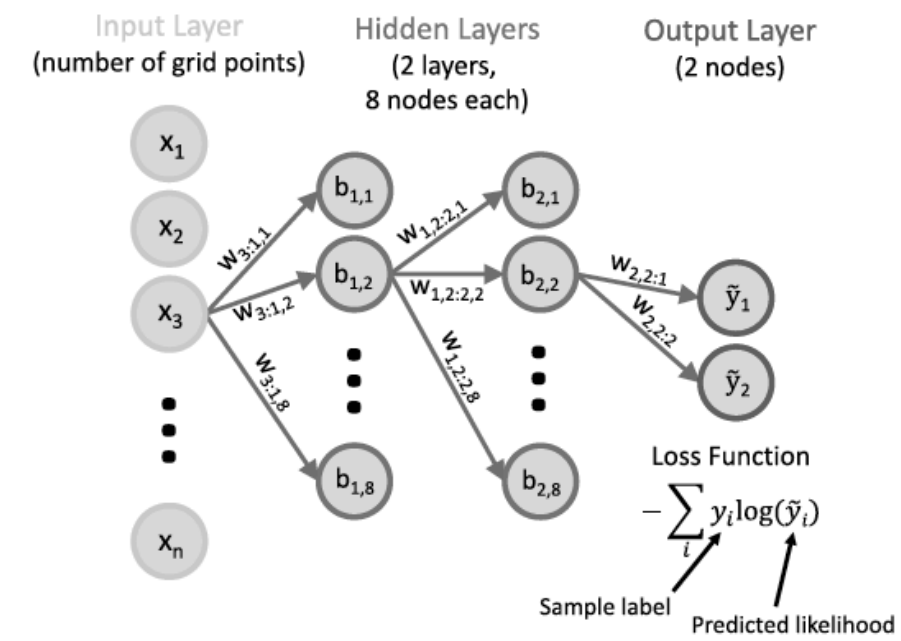
Hyperparameters such as nb. of neurons, nb. of layers...



Basics of neural networks, deep learning models

Developing CNN detector

Majstorović et. al., 2021, JGR



- 1 Training data
- 2 Training process
- 2 Modelling approach
- 3 NN architecture

Outline

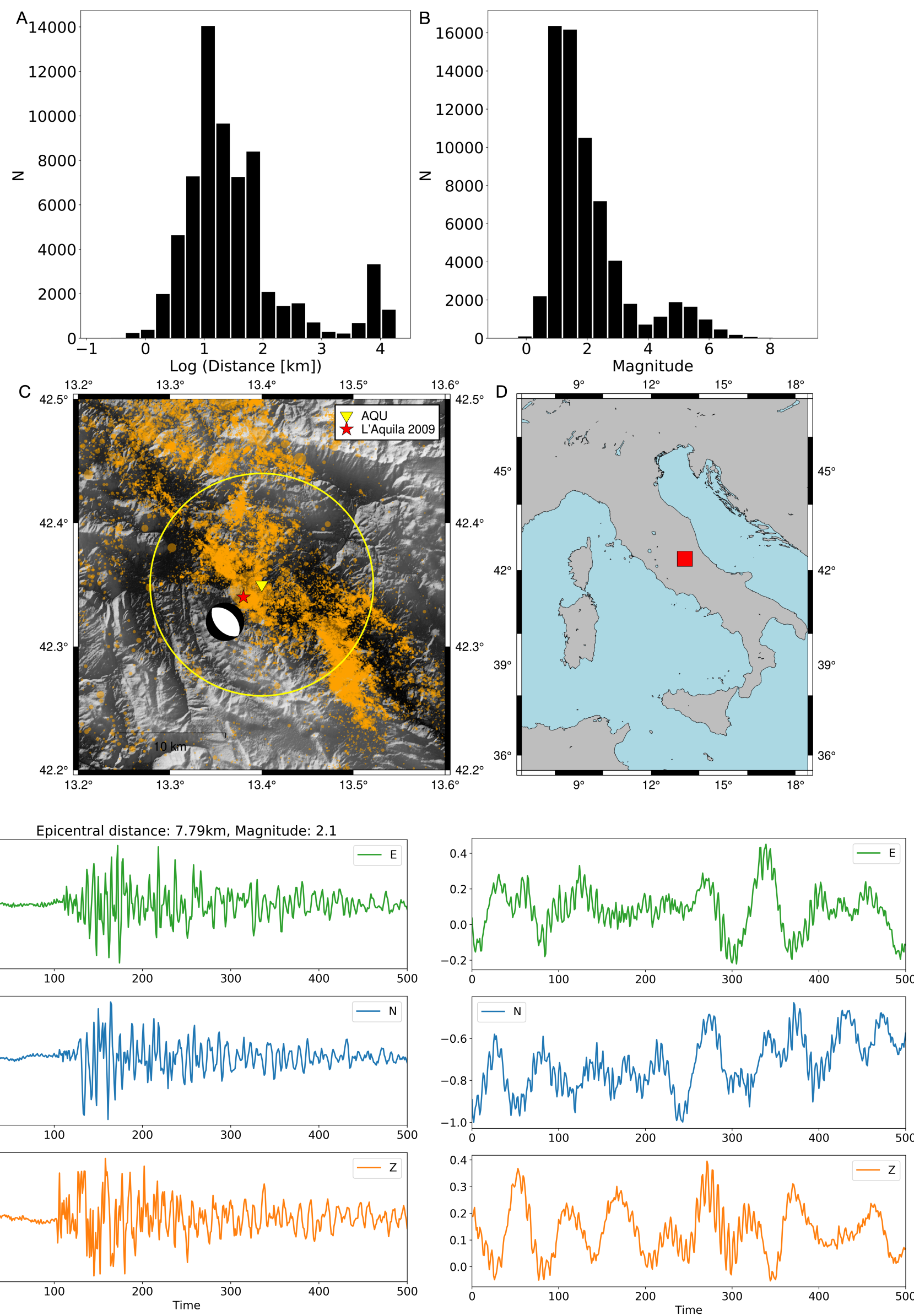
Introduction

CNN detector

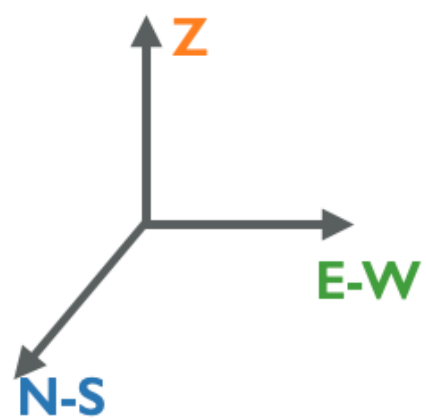
Interpretation

- 1 Training data
- 2 Training process
- 2 Modelling approach
- 3 NN architecture

1 Creating a database using one station approach.



65k positive samples + 65k negative samples

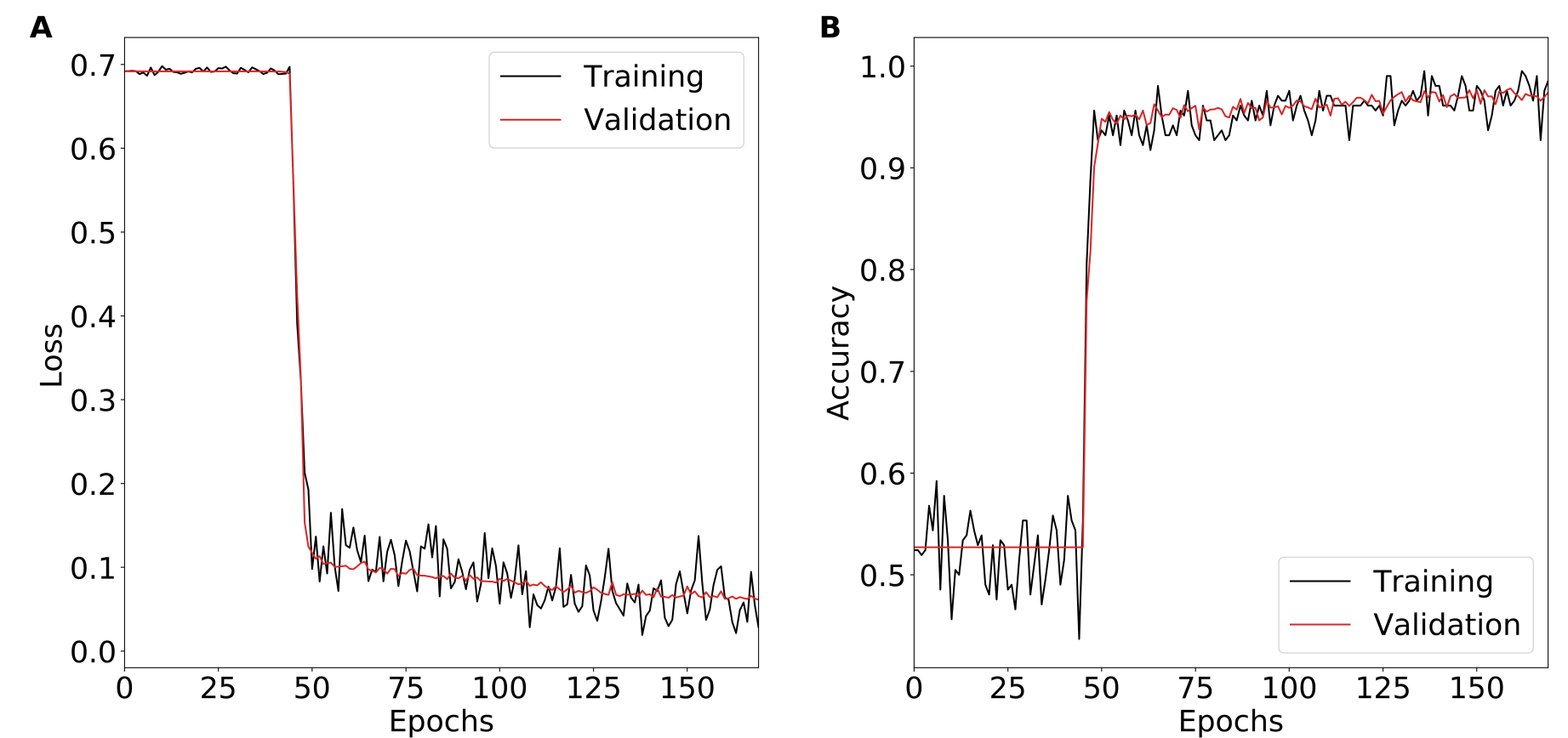


2 Classification task

- Positive class (earthquake)
- Negative class (noise)

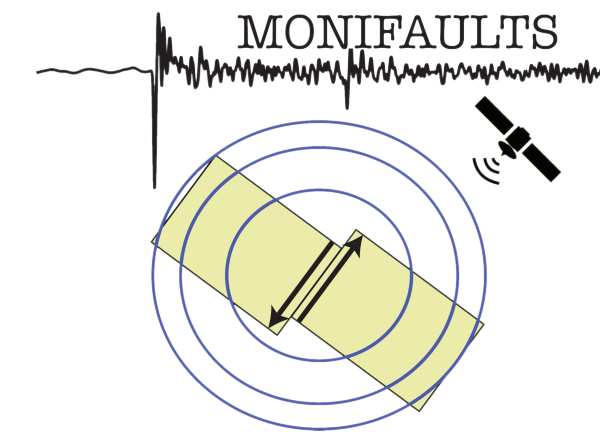
Convolutional neural network (CNN)

After a grid search analysis, the best combination of the training hyperparameters are selected.



The training hyperparameters

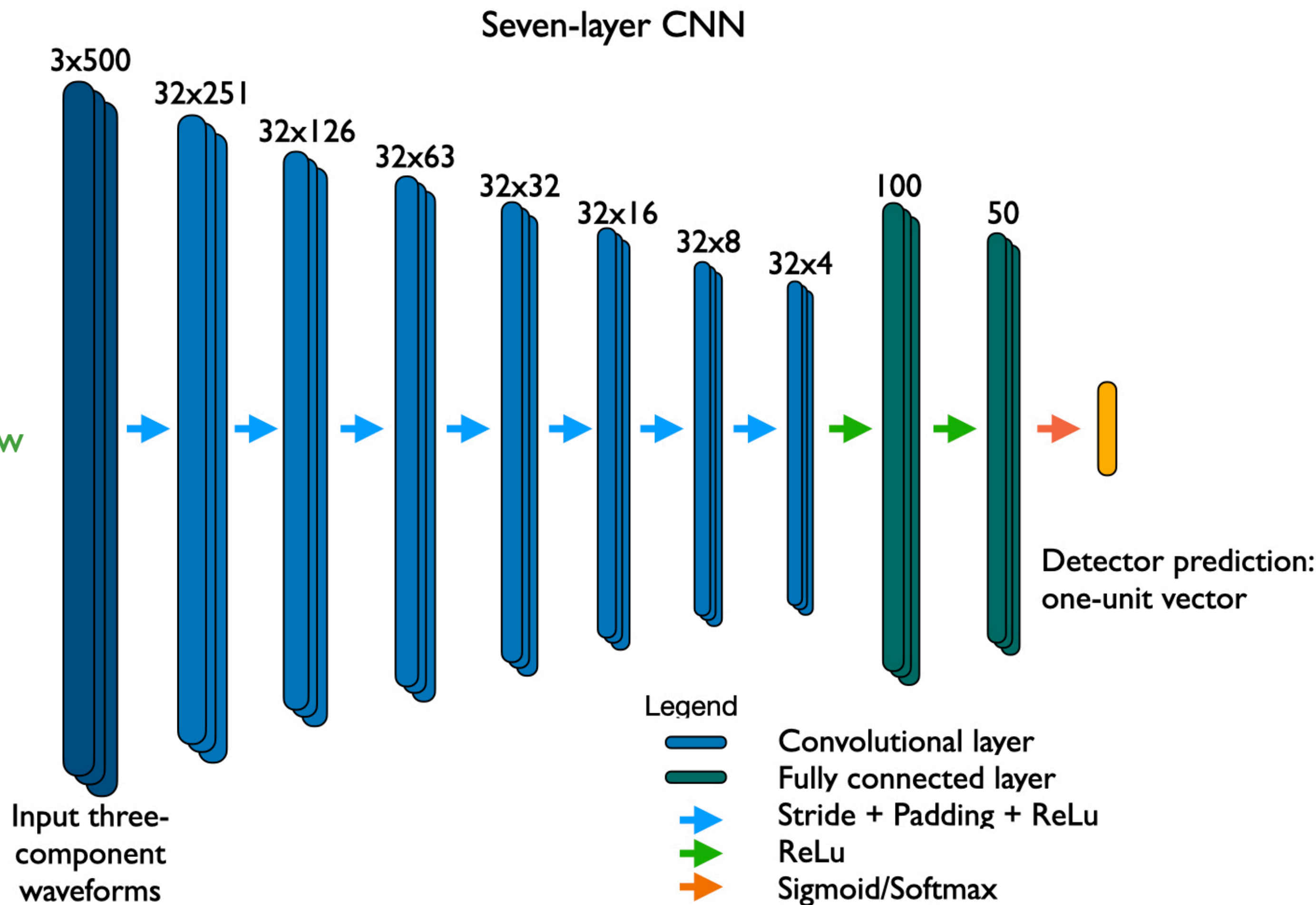
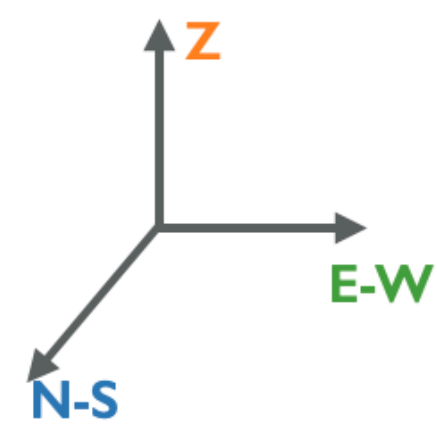
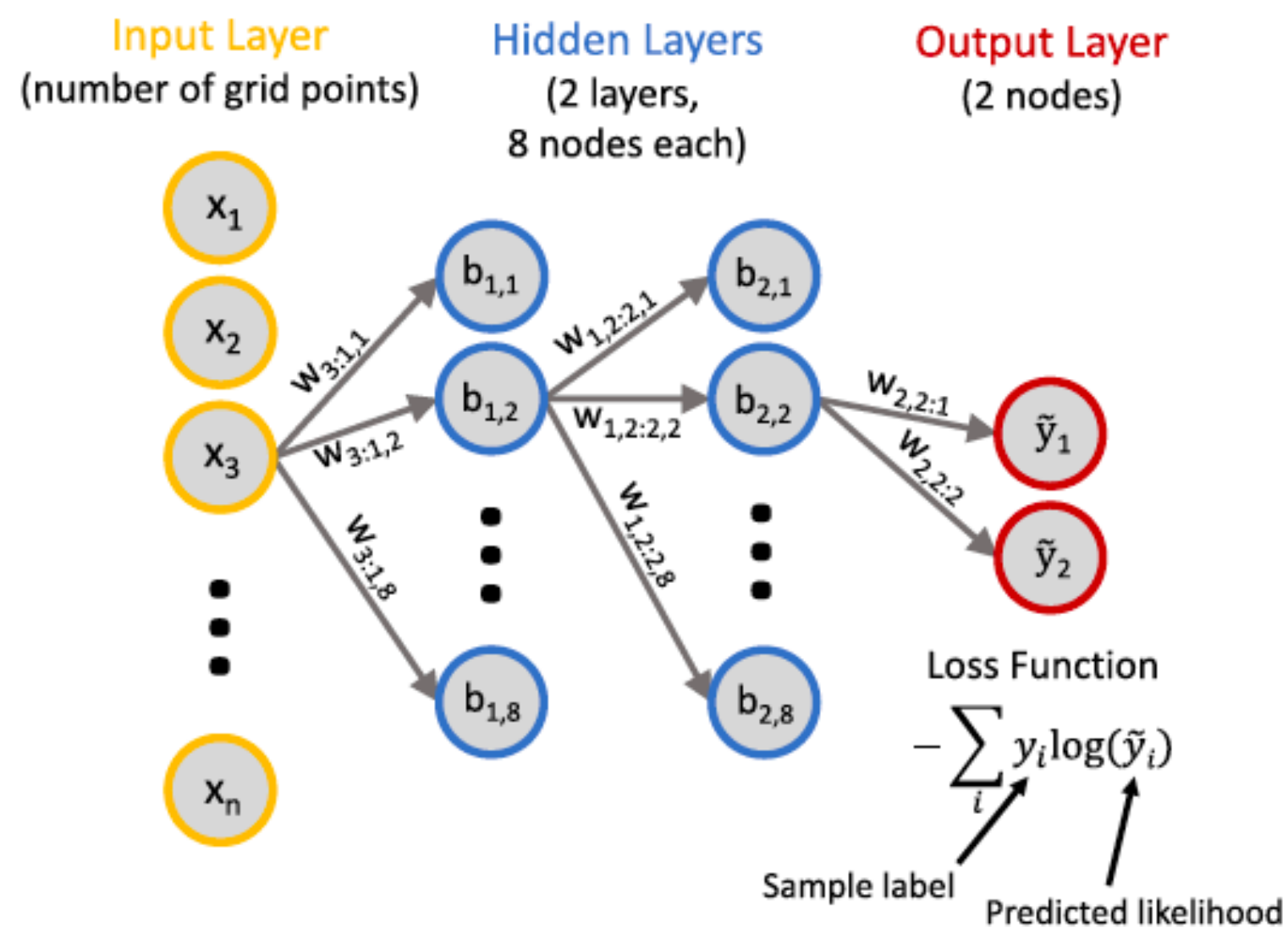
- Optimising algorithm SGD
- Learning rate $1e-2$
- Momentum 0.9
- Mini-batch 128



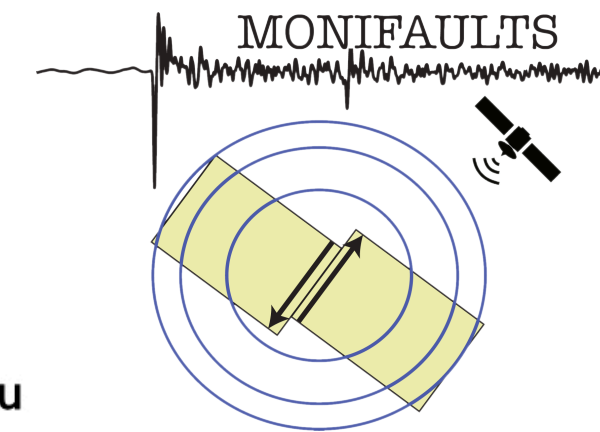
- 1 Training data
- 2 Training process
- 2 Modelling approach
- 3 NN architecture

3 Convolutional neural network (deep learning) - supervised training process

Convolutional layers
 Pooling layers
 Fully-connected layers



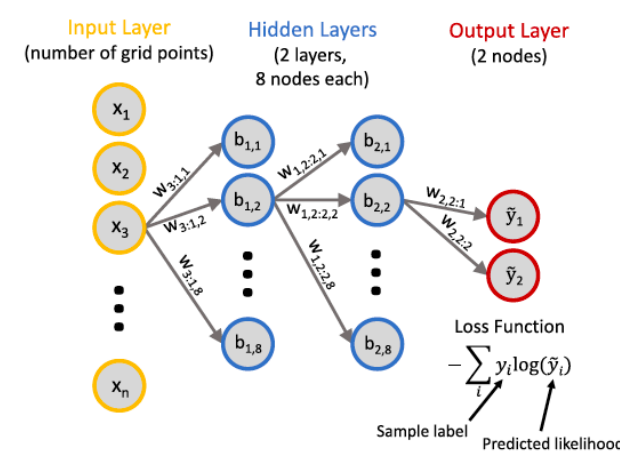
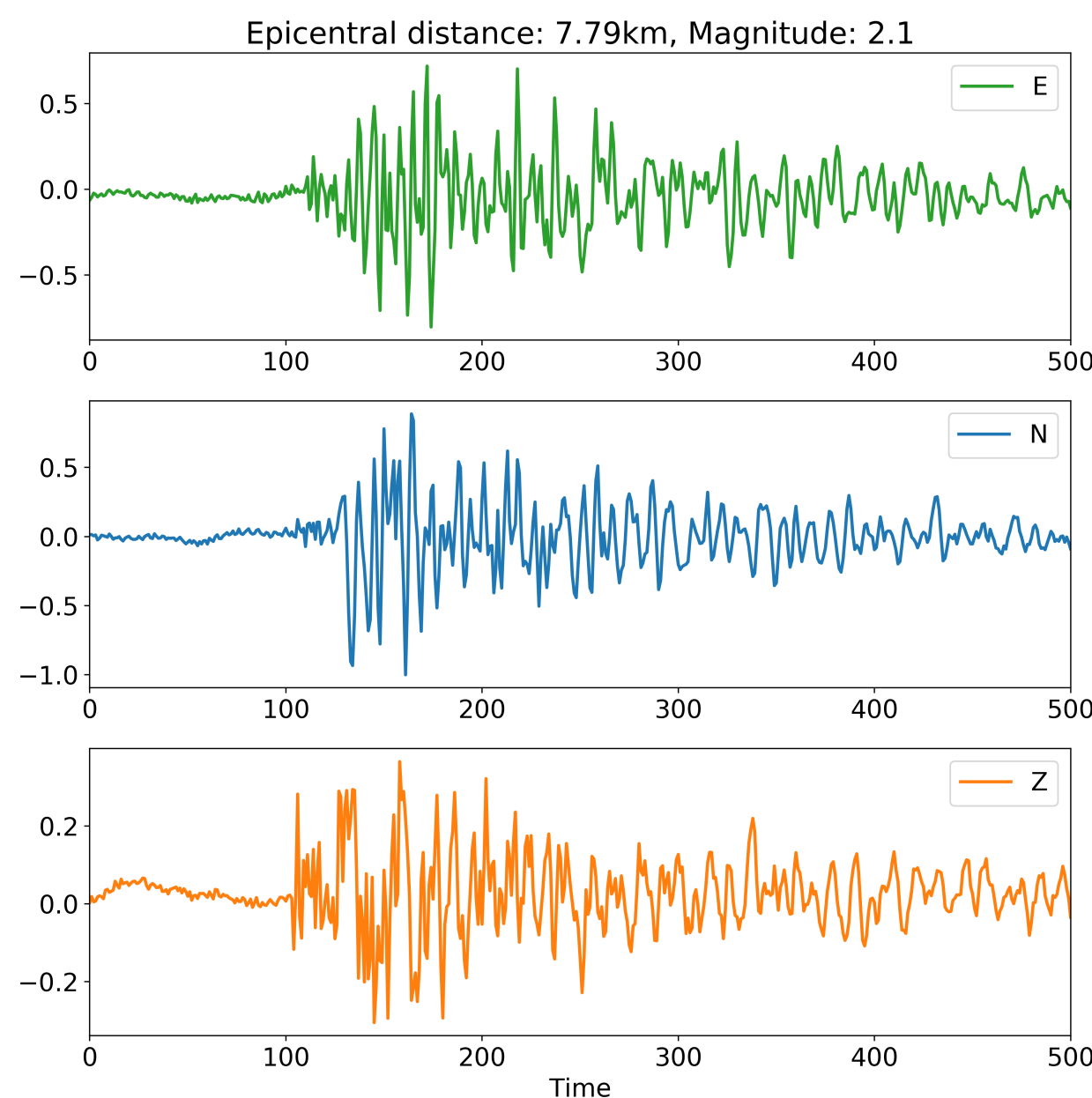
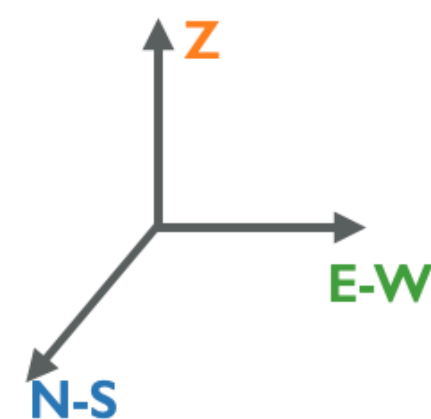
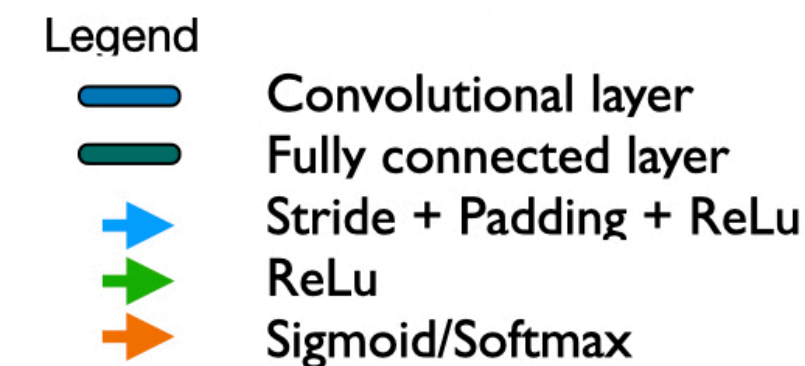
36k of trainable parameters



- 1 Training data
- 2 Training process
- 2 Modelling approach
- 3 NN architecture

3 Convolutional neural network (deep learning) - supervised training process

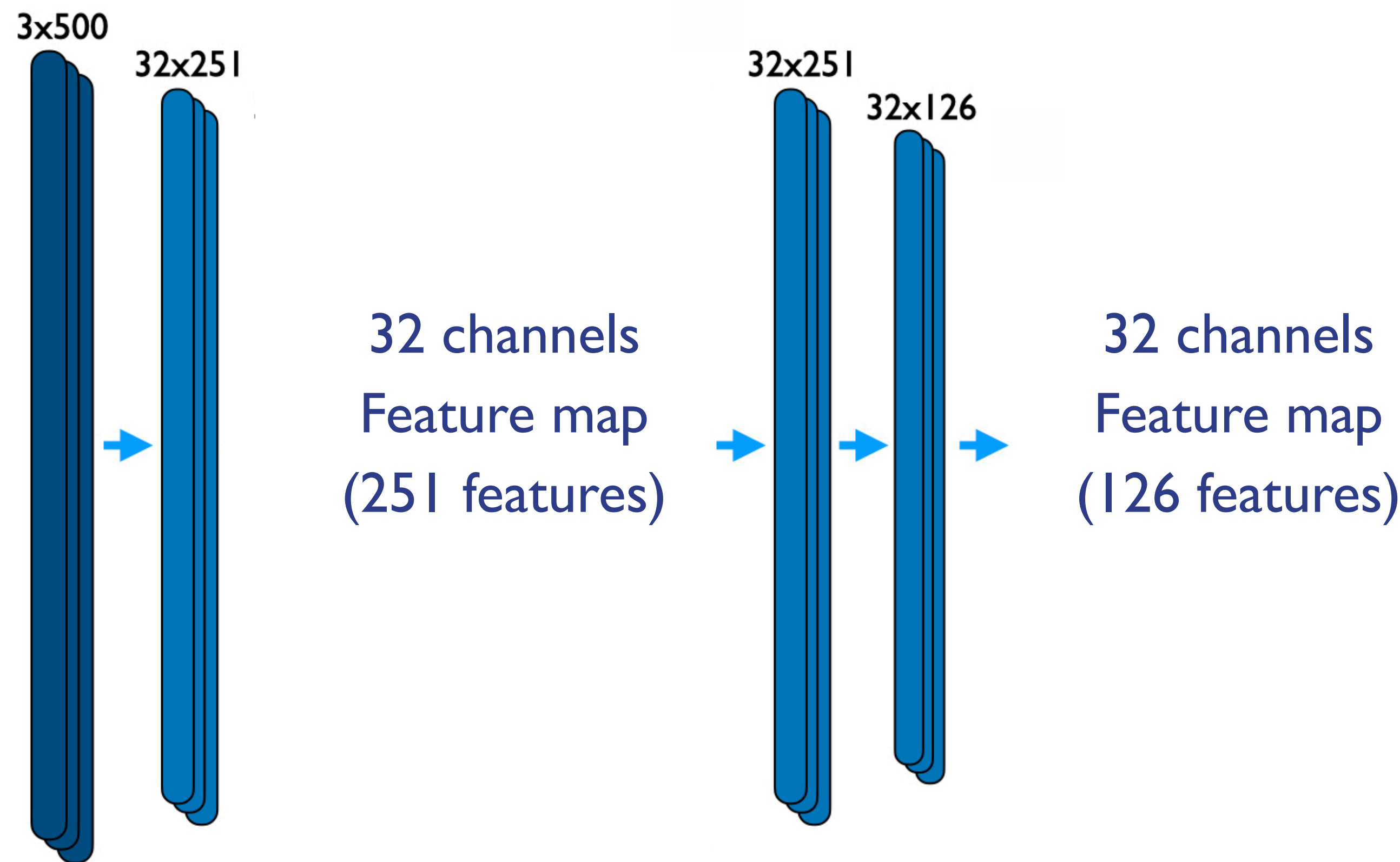
Convolutional layers



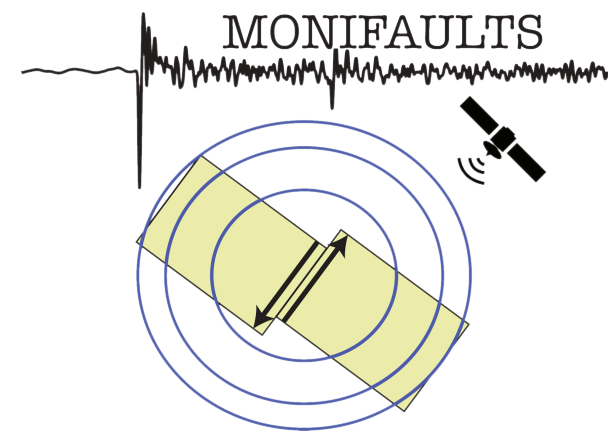
Input array
3 channels x 500 samples

Filter (kernel) size
3 x 3 x 32

Filter (kernel) size
3 x 32 x 32



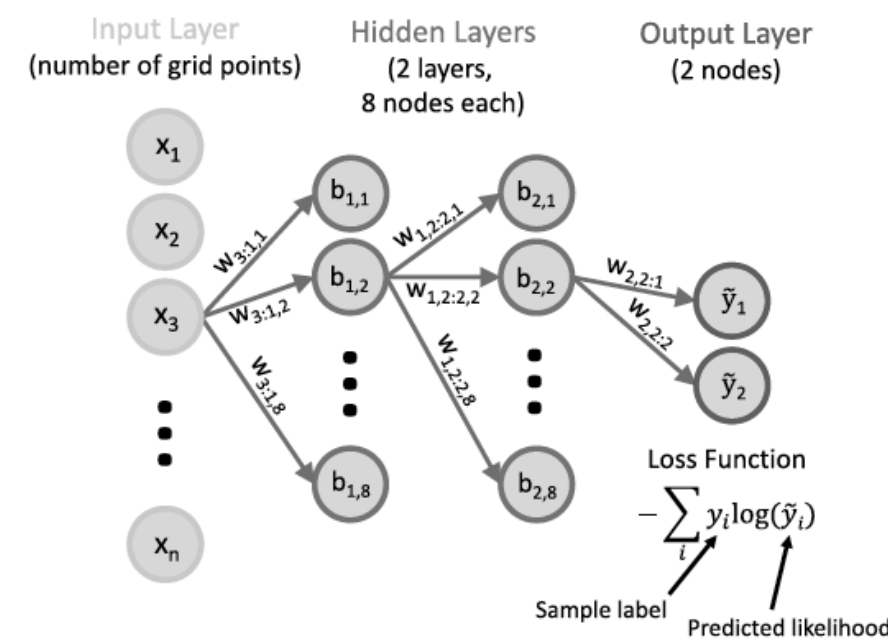
$$f \times C_{in} \times C_{out}$$



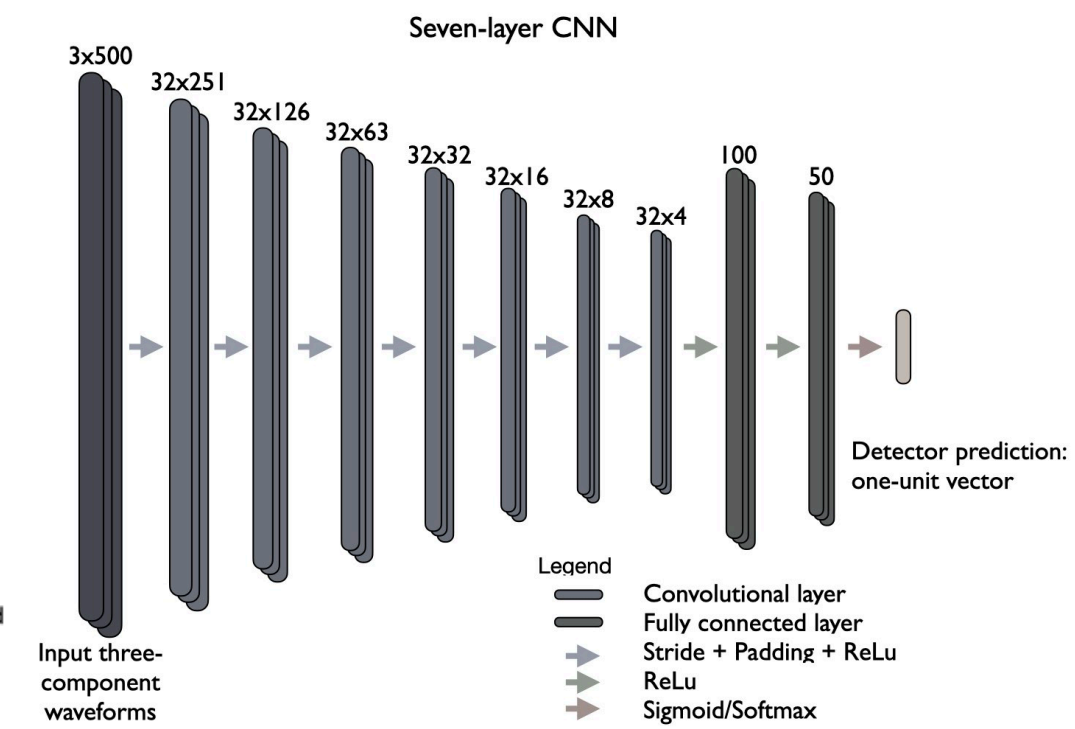
Basics of neural networks, deep learning models

Developing CNN detector

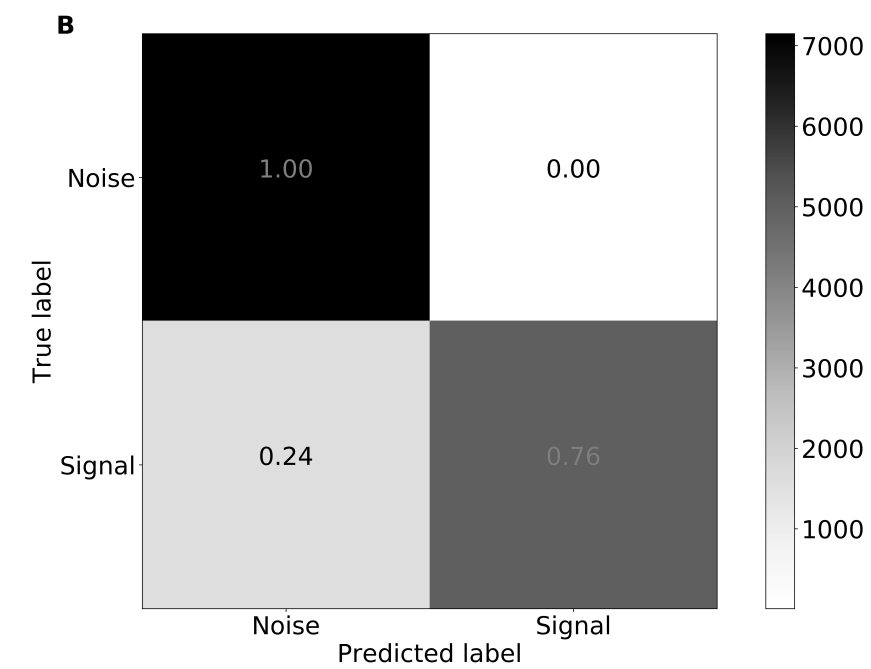
What does interpretation stand for in DL?

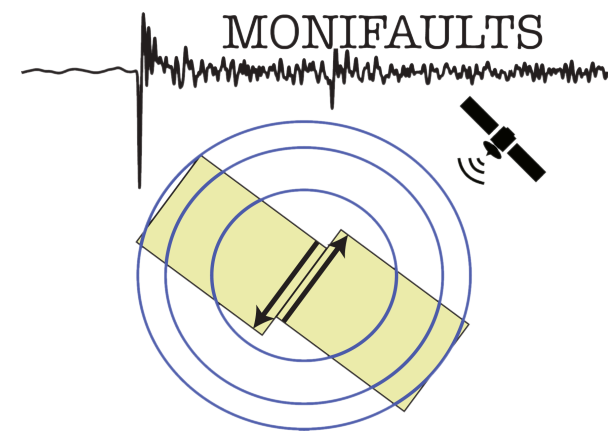


Majstorović et al., 2021, JGR



- 1 Training data
- 2 Training process
- 2 Modelling approach
- 3 NN architecture



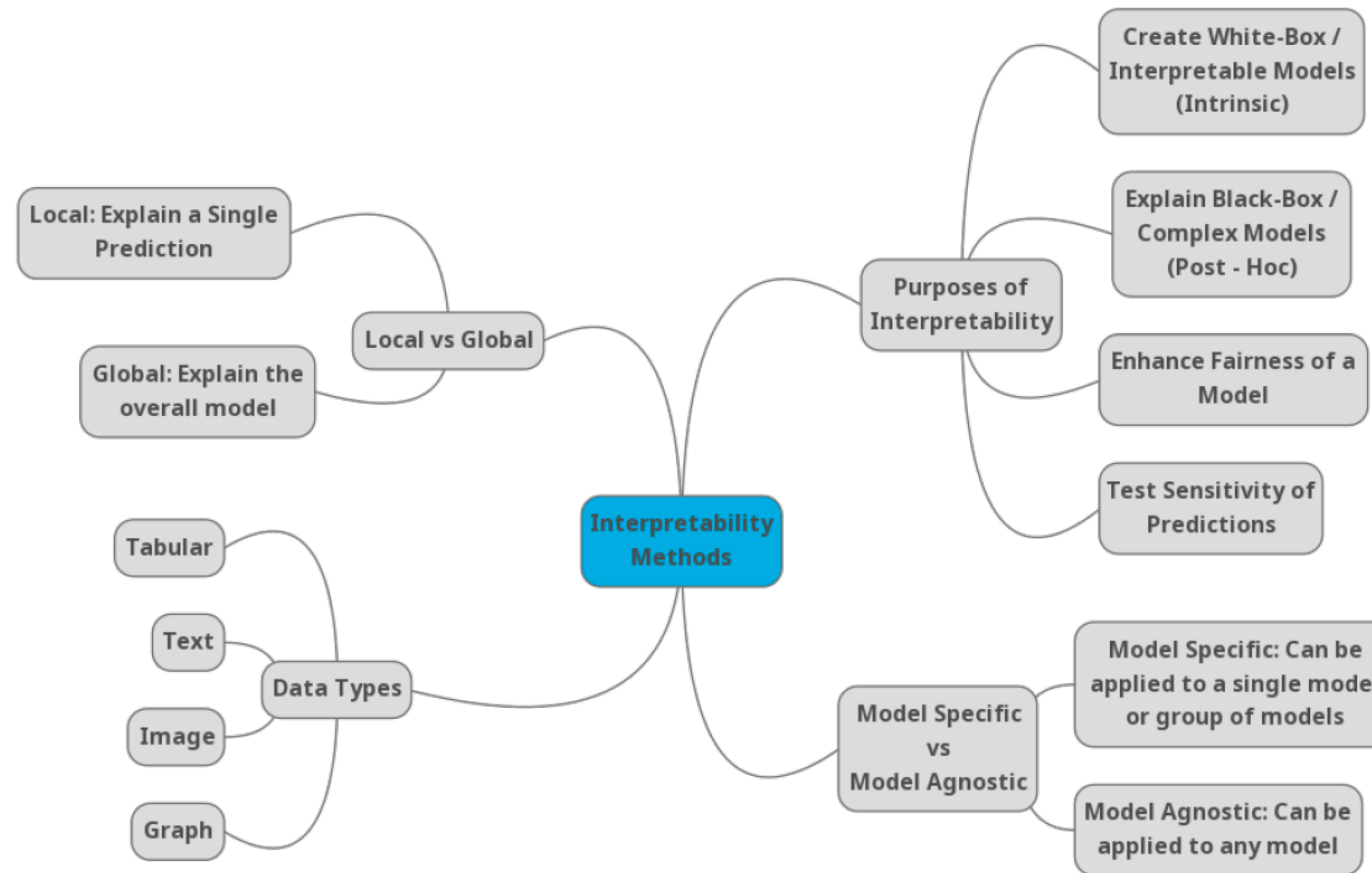


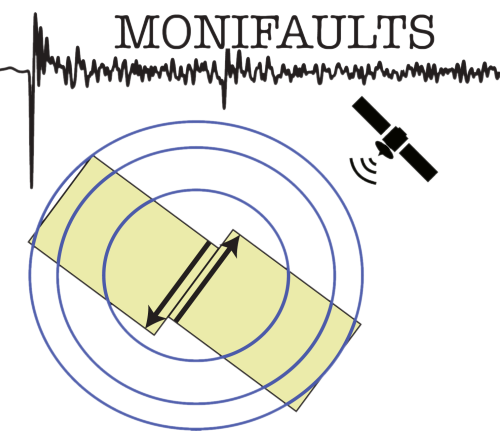
ML (NN, DL) models are often criticised by end users as being a “**black box**” because of the perceived inability to understand how ML makes its prediction.

Feature visualisation

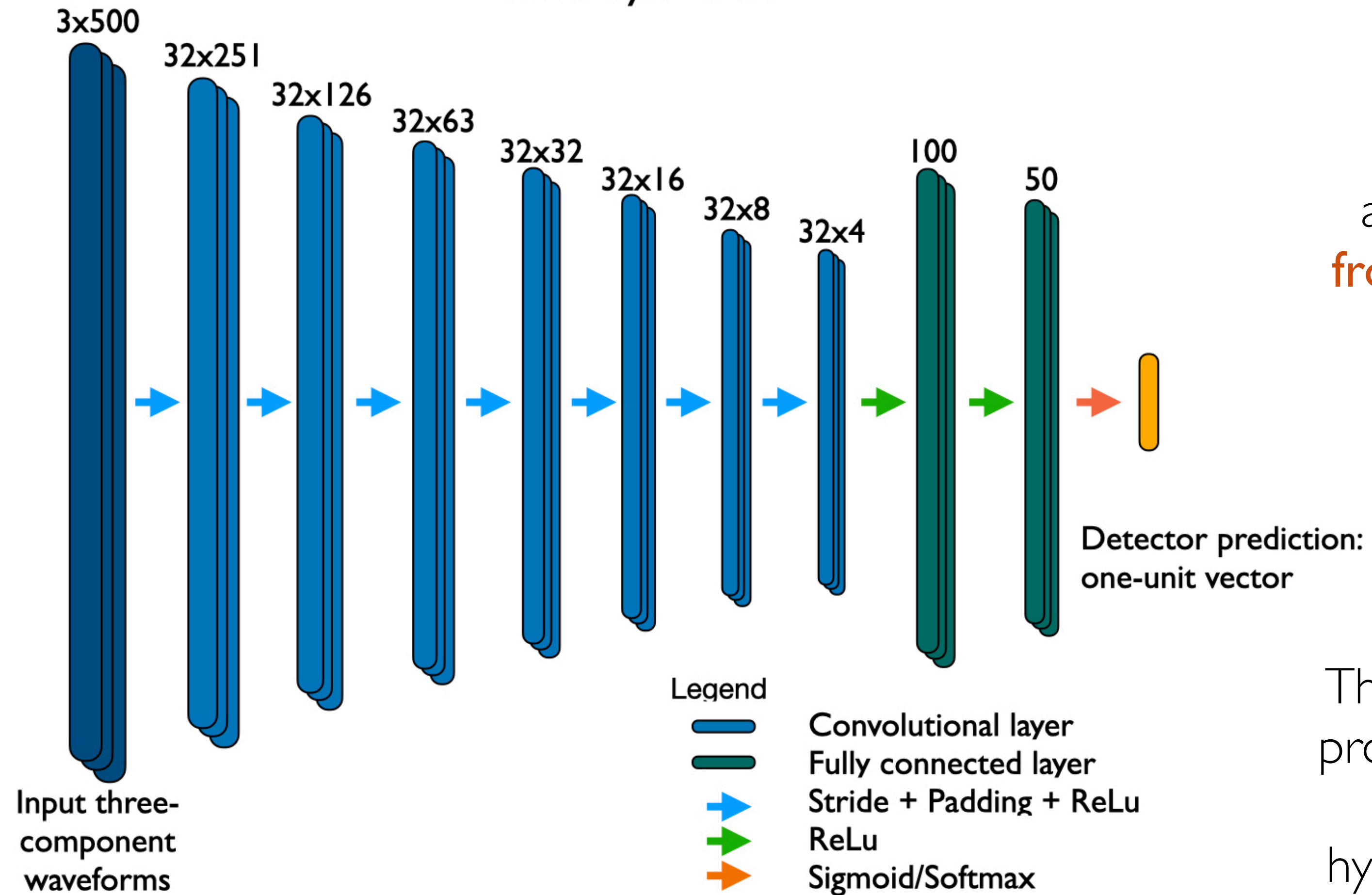
Backward optimisation

Layer-wise relevance method





Seven-layer CNN



The **weights and biases** that define the kernels (the filters) and that are being adjusted in the training process **are now frozen** to investigate how those impact the input data.

The training of the DL model is a stochastic process - repeating the training process with the same dataset and the same hyperparameters yields different weights and biases.

Outline

Introduction

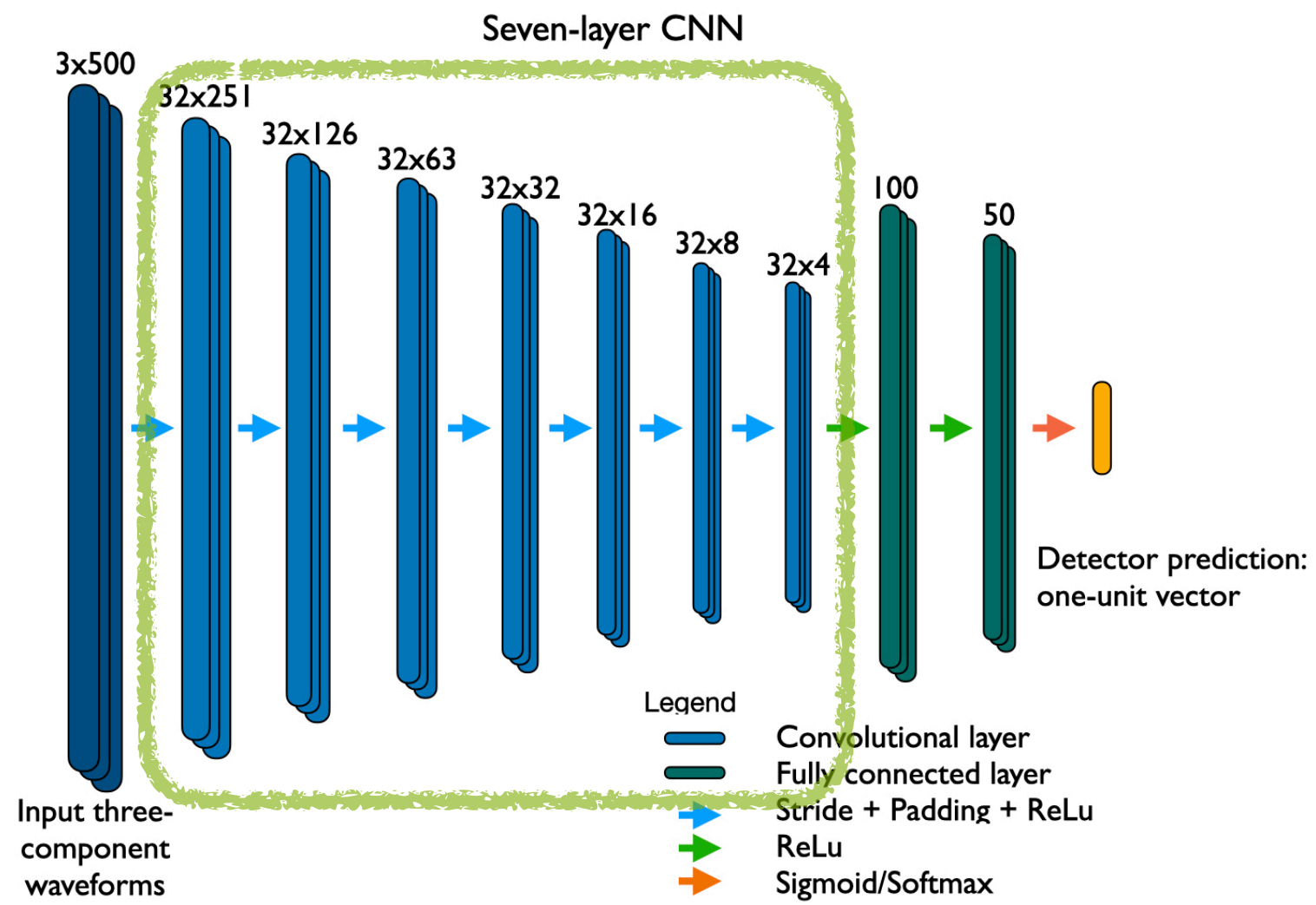
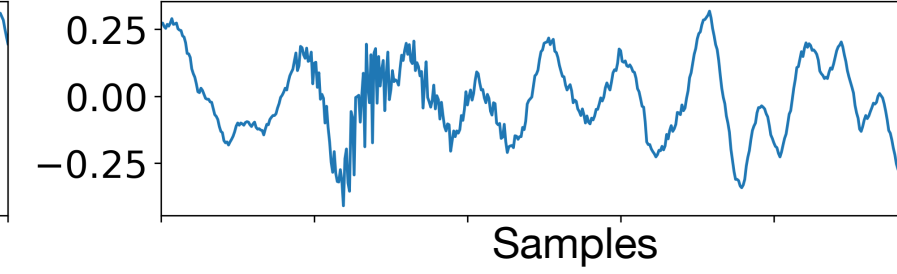
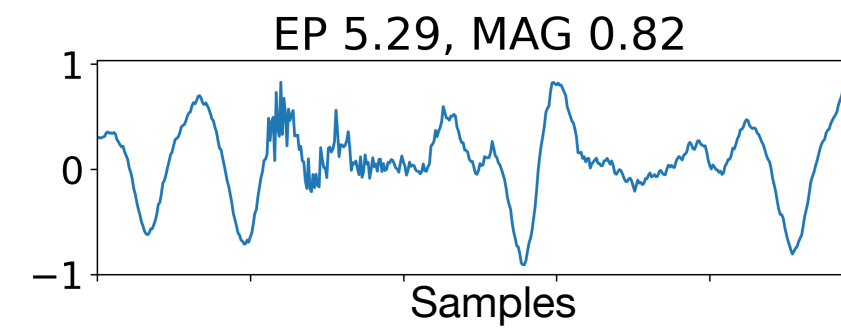
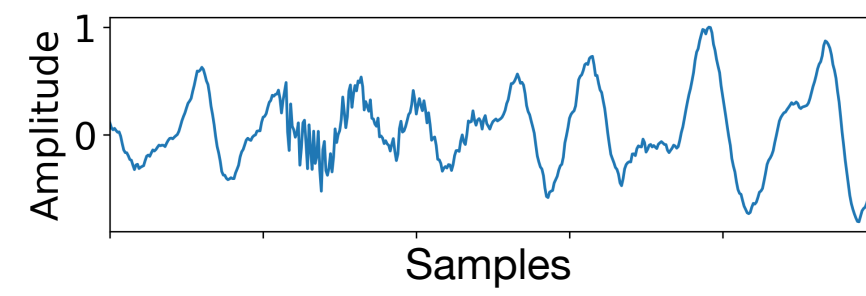
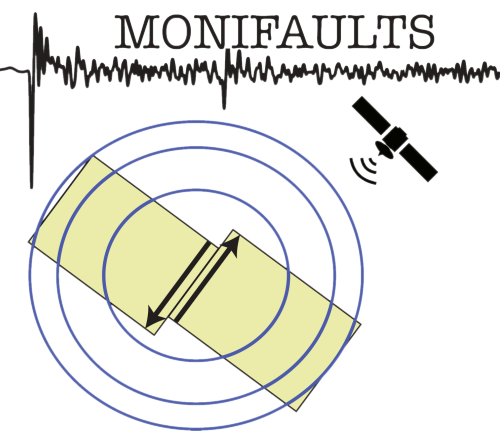
CNN detector

Interpretation

Feature visualisation

Backward optimisation

Layer-wise relevance method



Kernel visualisation

Feature map visualisation

Outline

Introduction

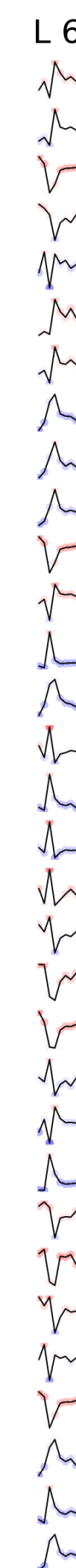
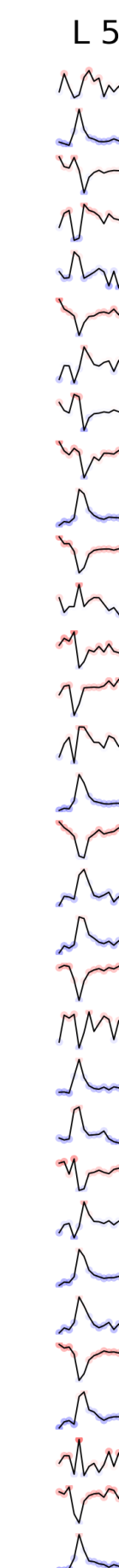
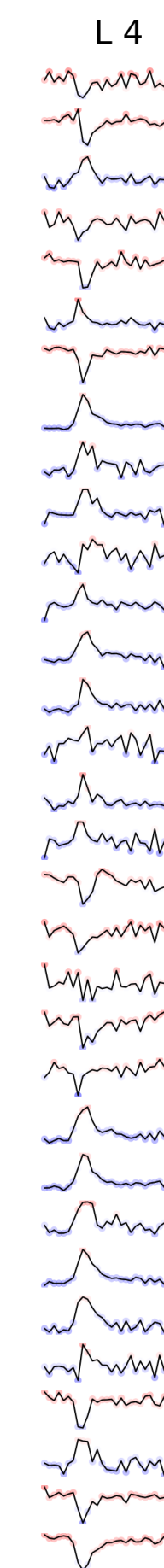
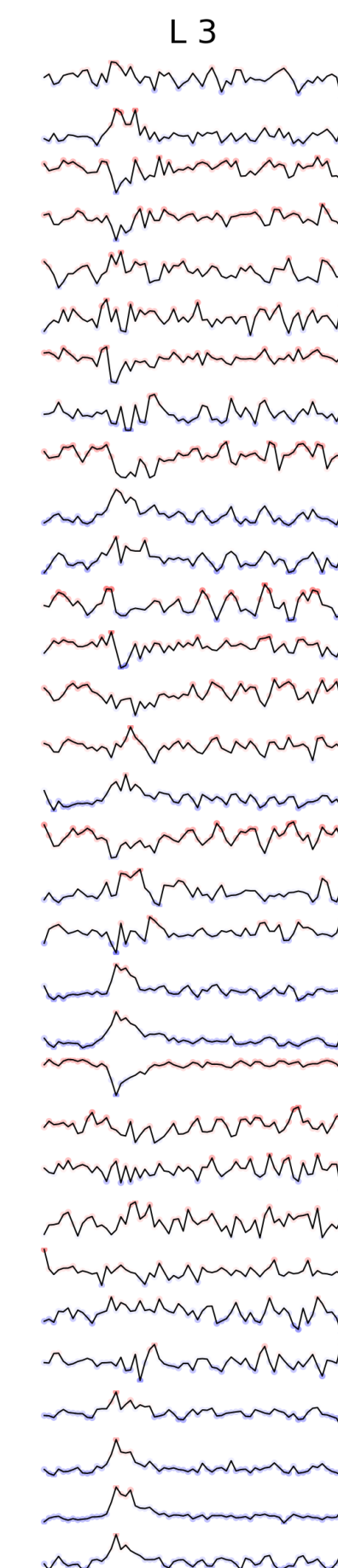
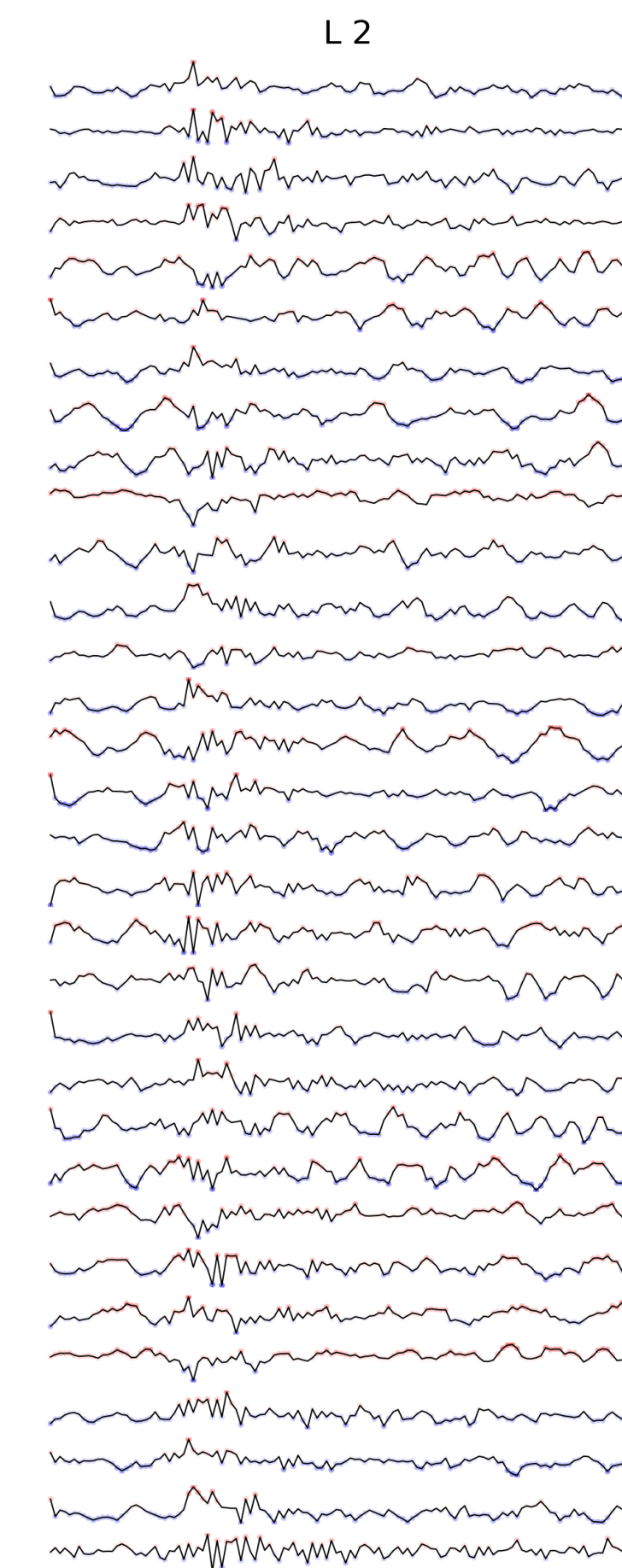
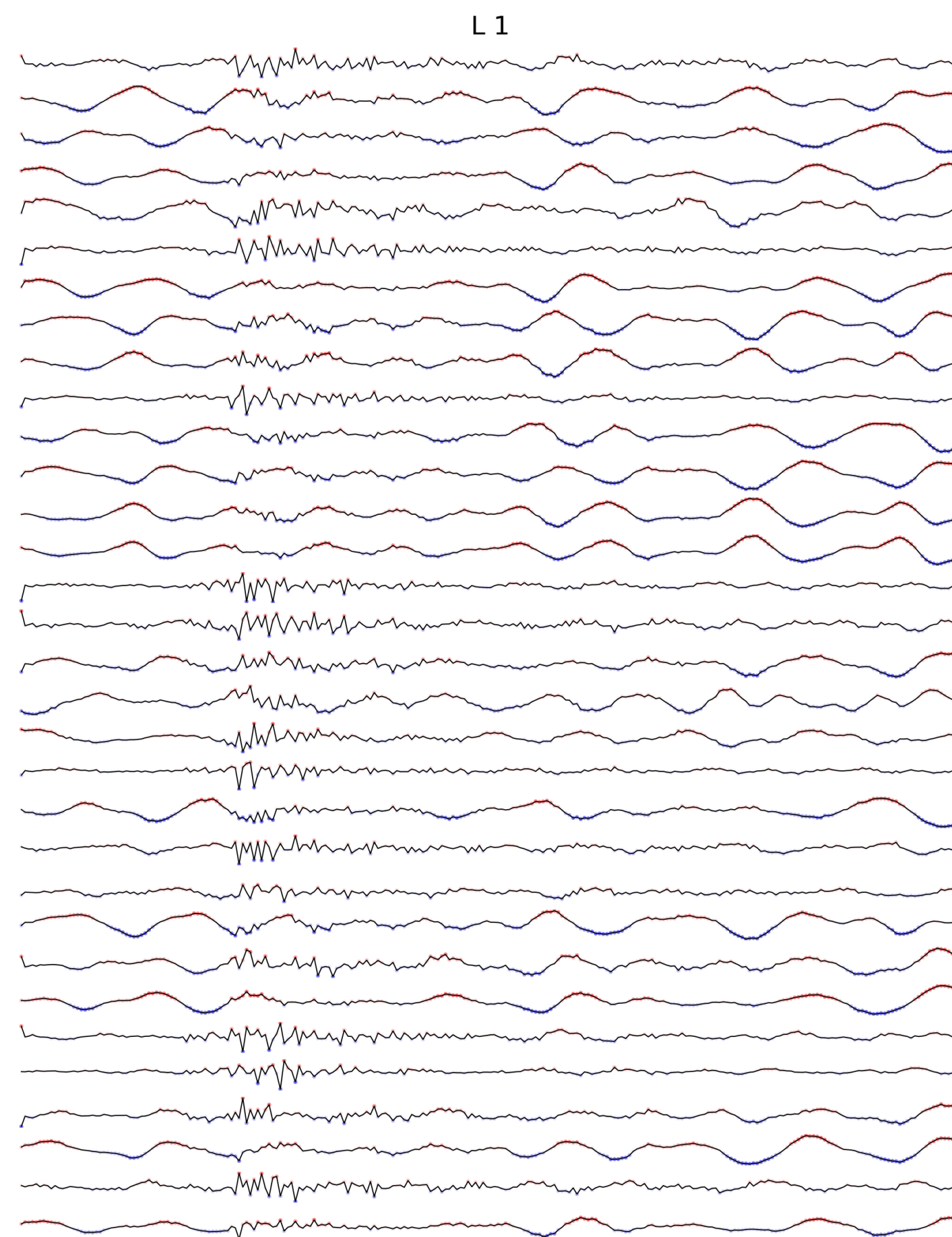
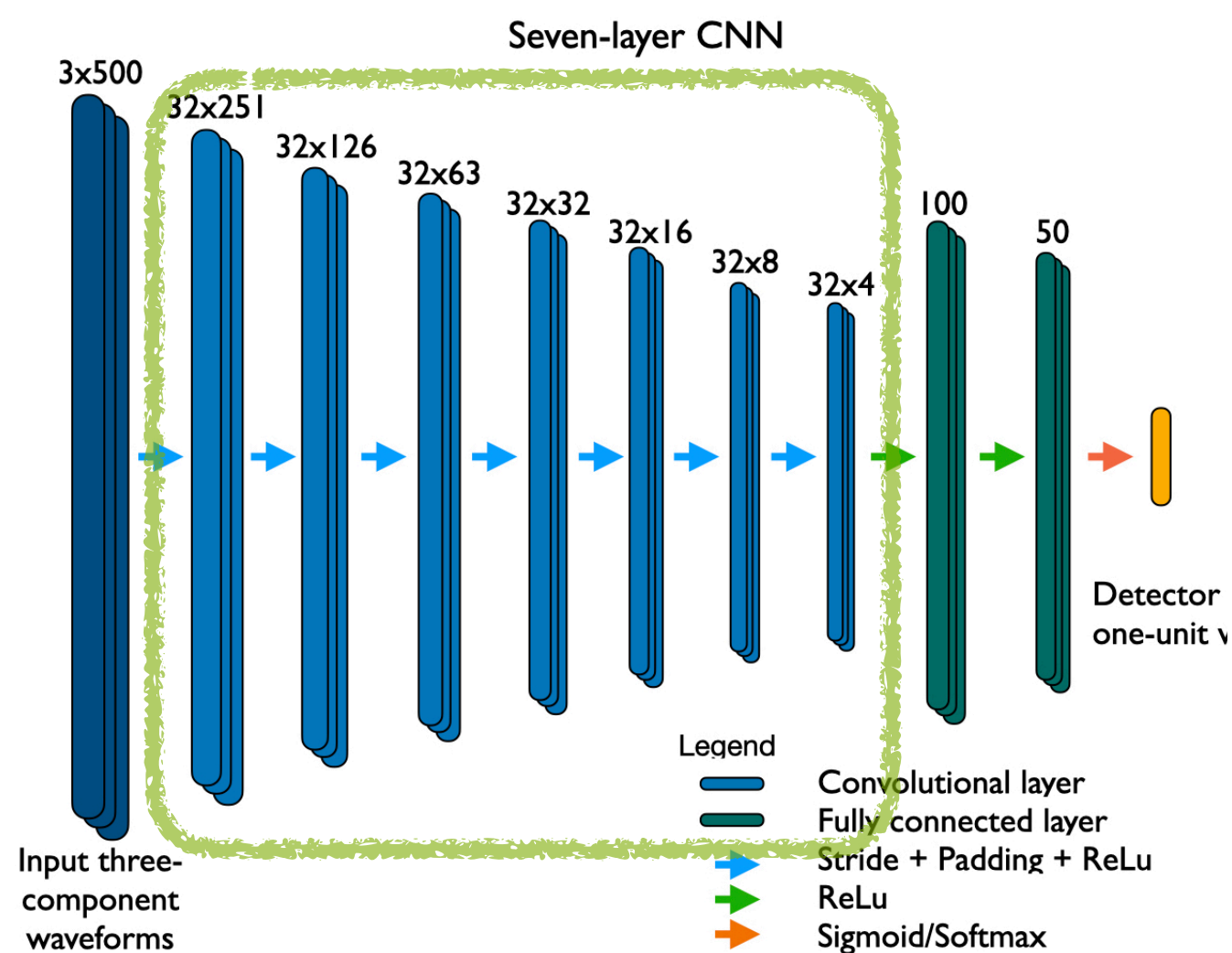
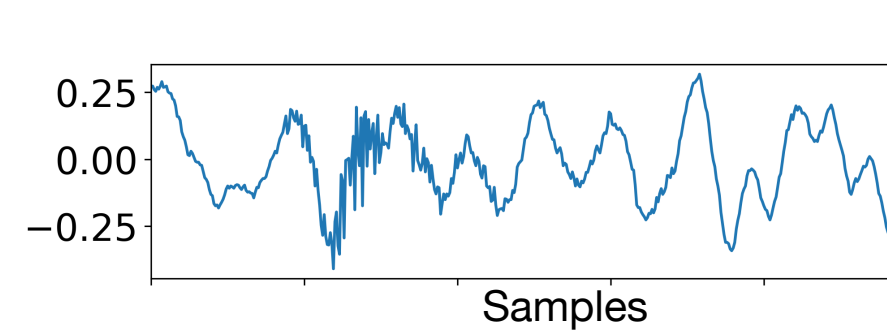
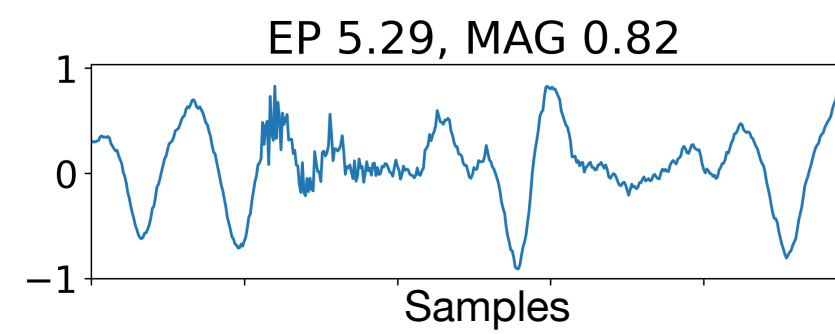
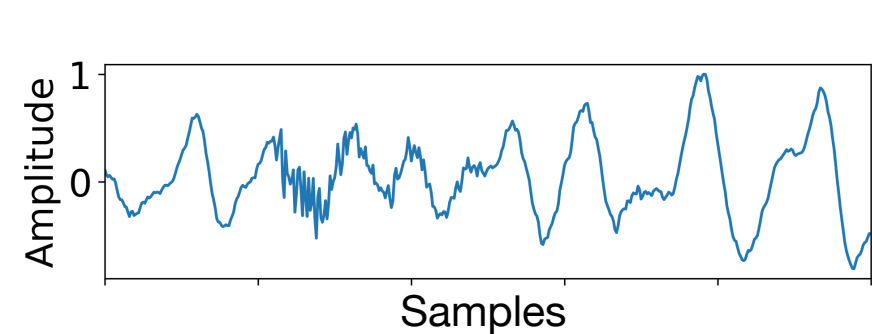
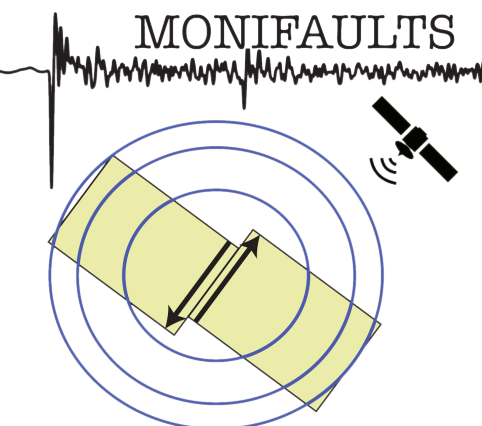
CNN detector

Interpretation

Feature visualisation

Backward optimisation

Layer-wise relevance method



Kernel visualisation

Feature map visualisation

251 features

126 features

63 ft.

32 ft.

16 ft.

8 ft.

4 ft.

Outline

Introduction

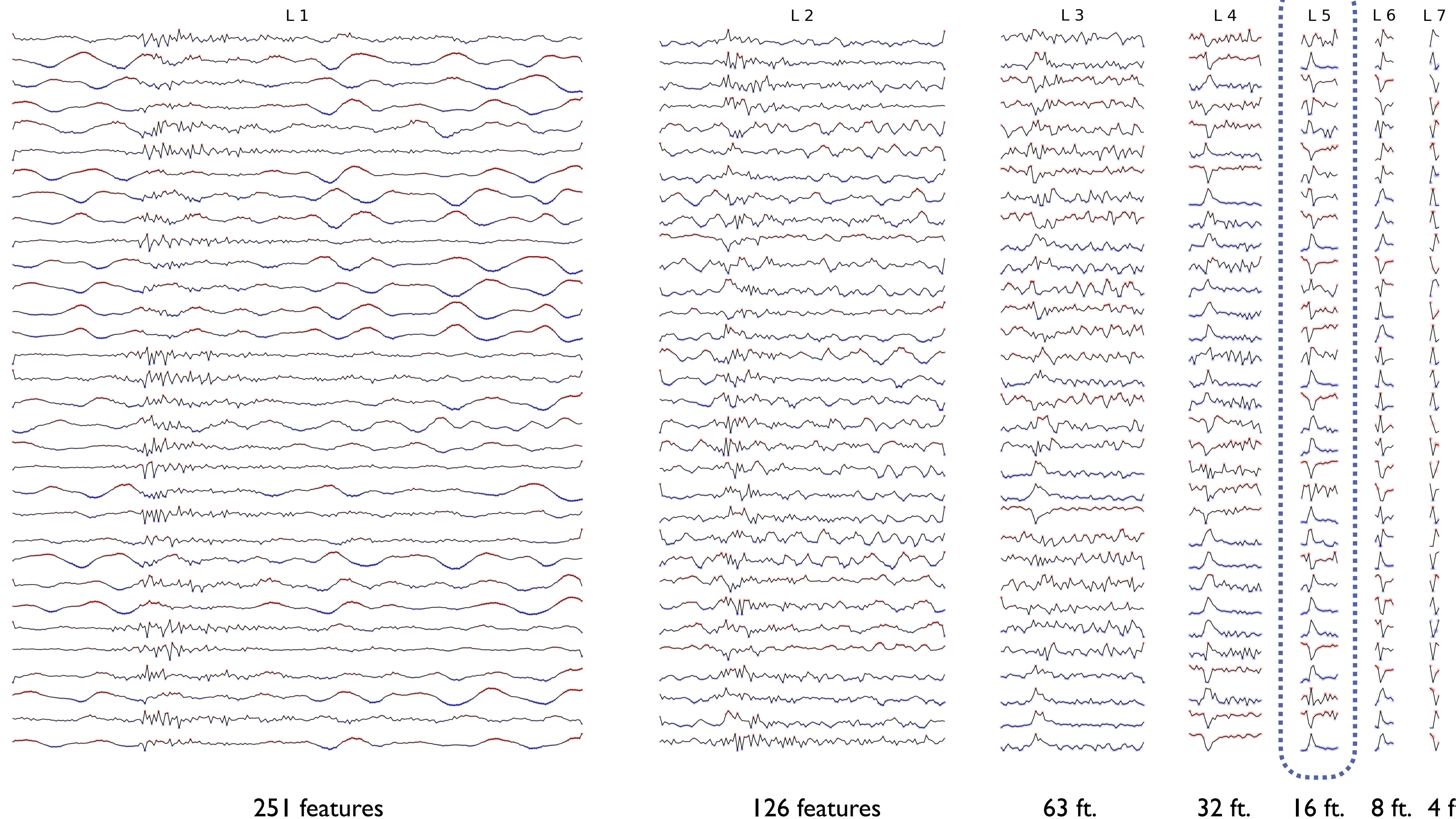
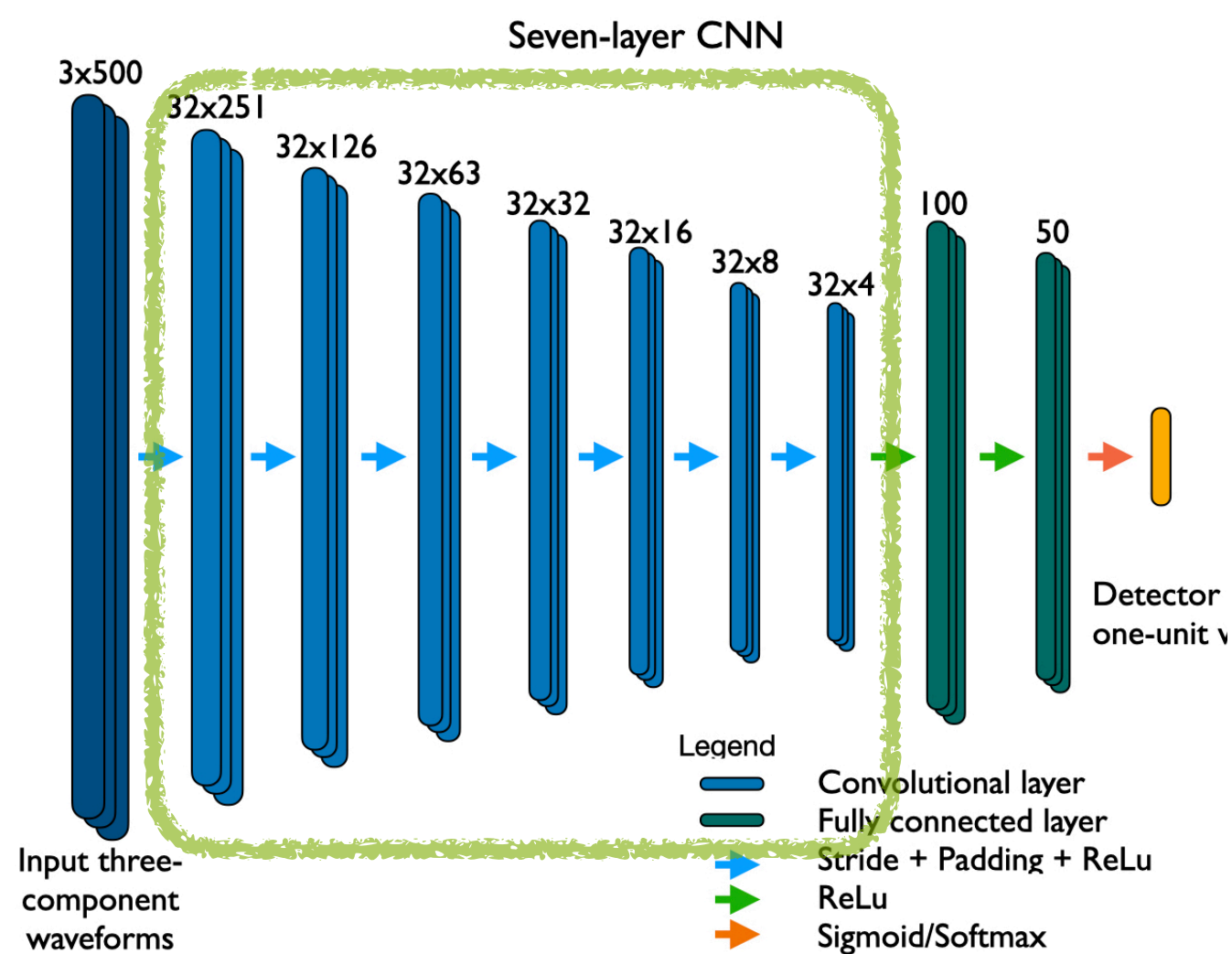
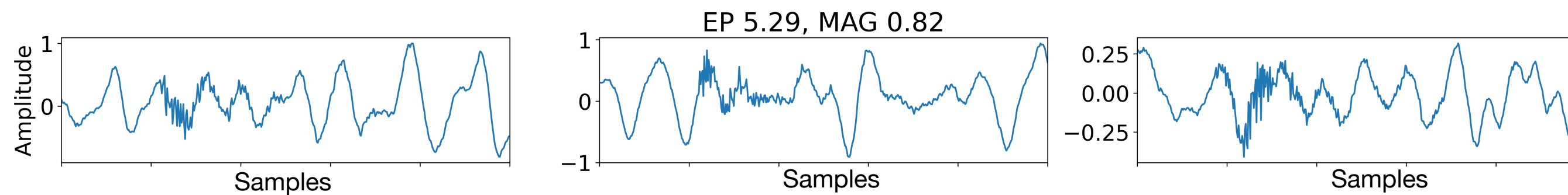
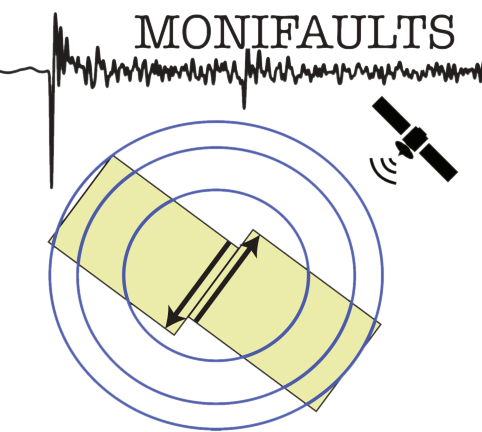
CNN detector

Interpretation

Feature visualisation

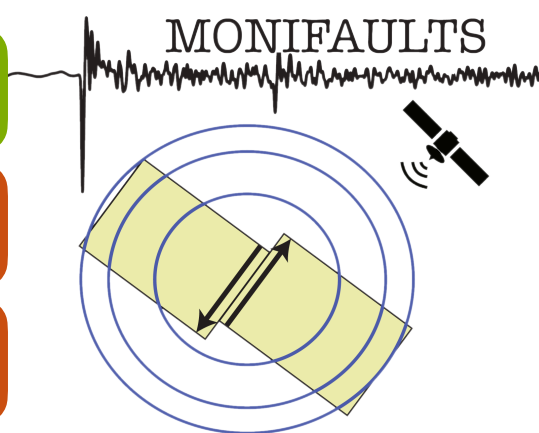
Backward optimisation

Layer-wise relevance method



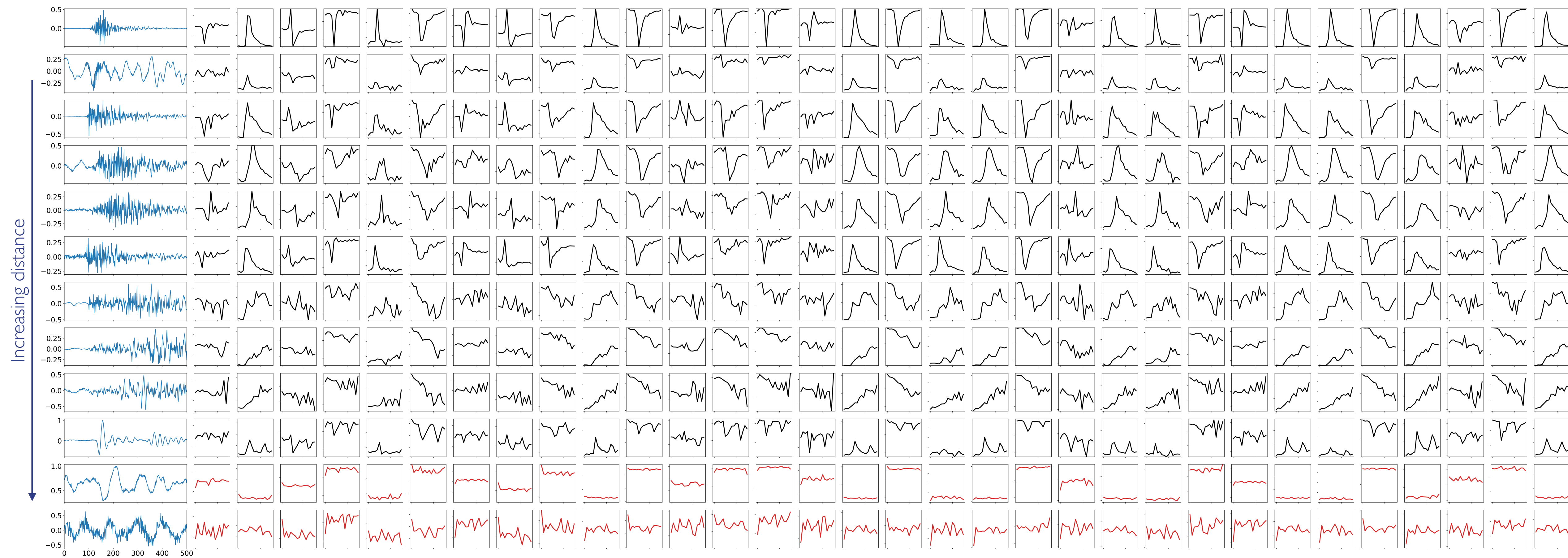
Kernel visualisation

Feature map visualisation



Z component

Y axis is the same per column/channel



Outline

Introduction

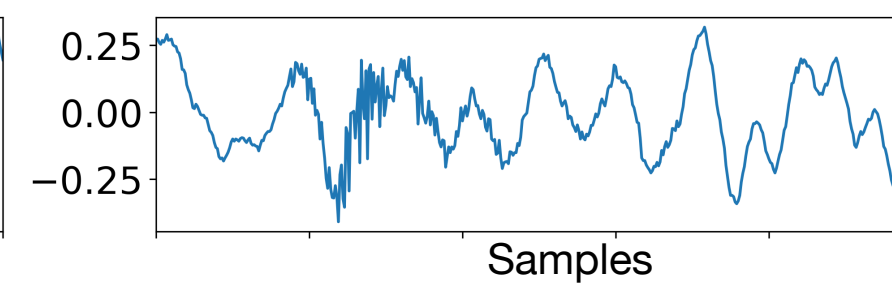
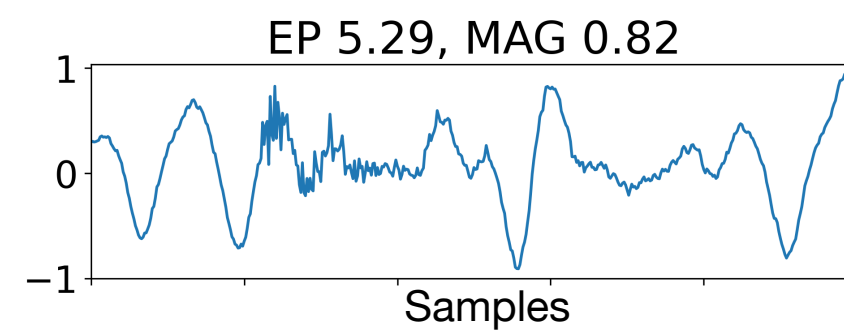
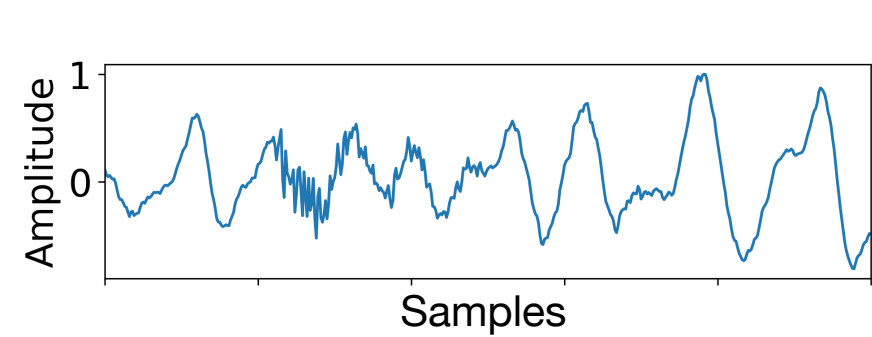
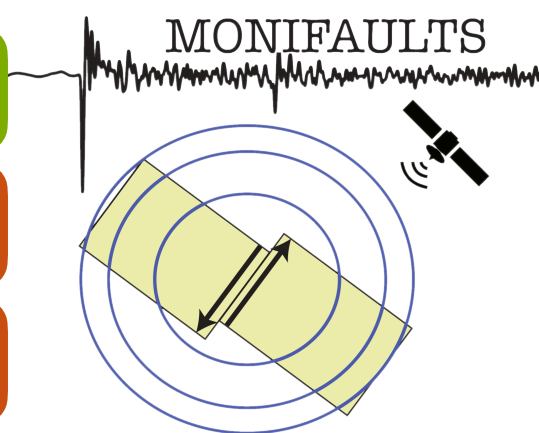
CNN detector

Interpretation

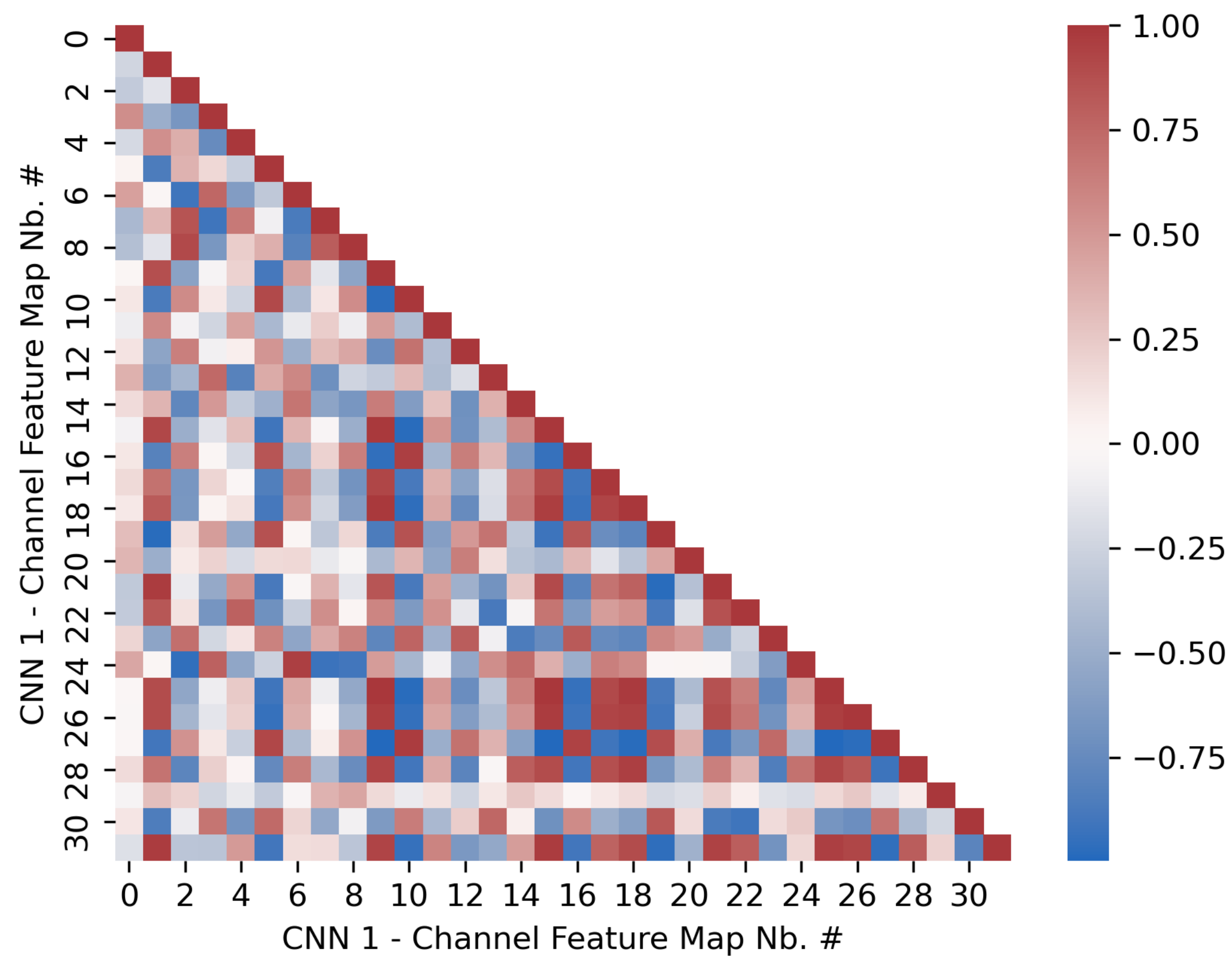
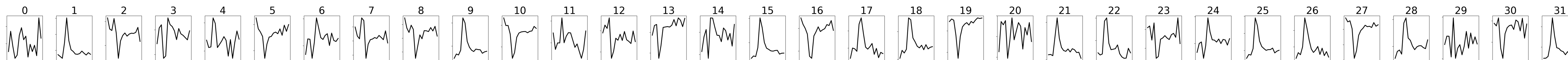
Feature visualisation

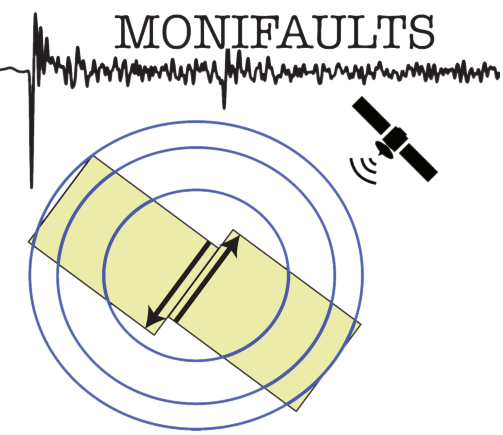
Backward optimisation

Layer-wise relevance method



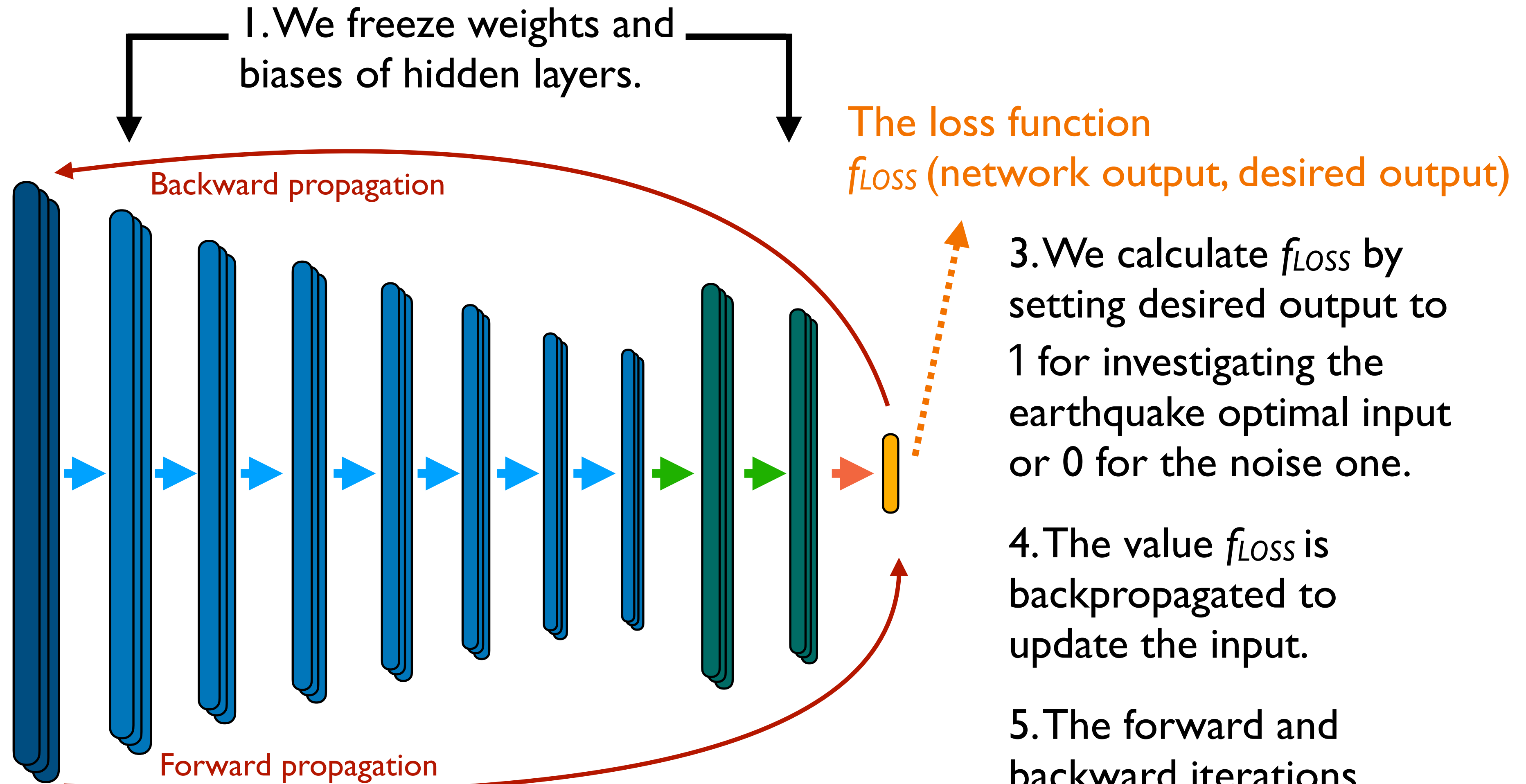
CNN 1





1. We freeze weights and biases of hidden layers.

2. We either use
a) zero,
b) random,
c) real input
and forward propagate
it to the output layer.



Outline

Introduction

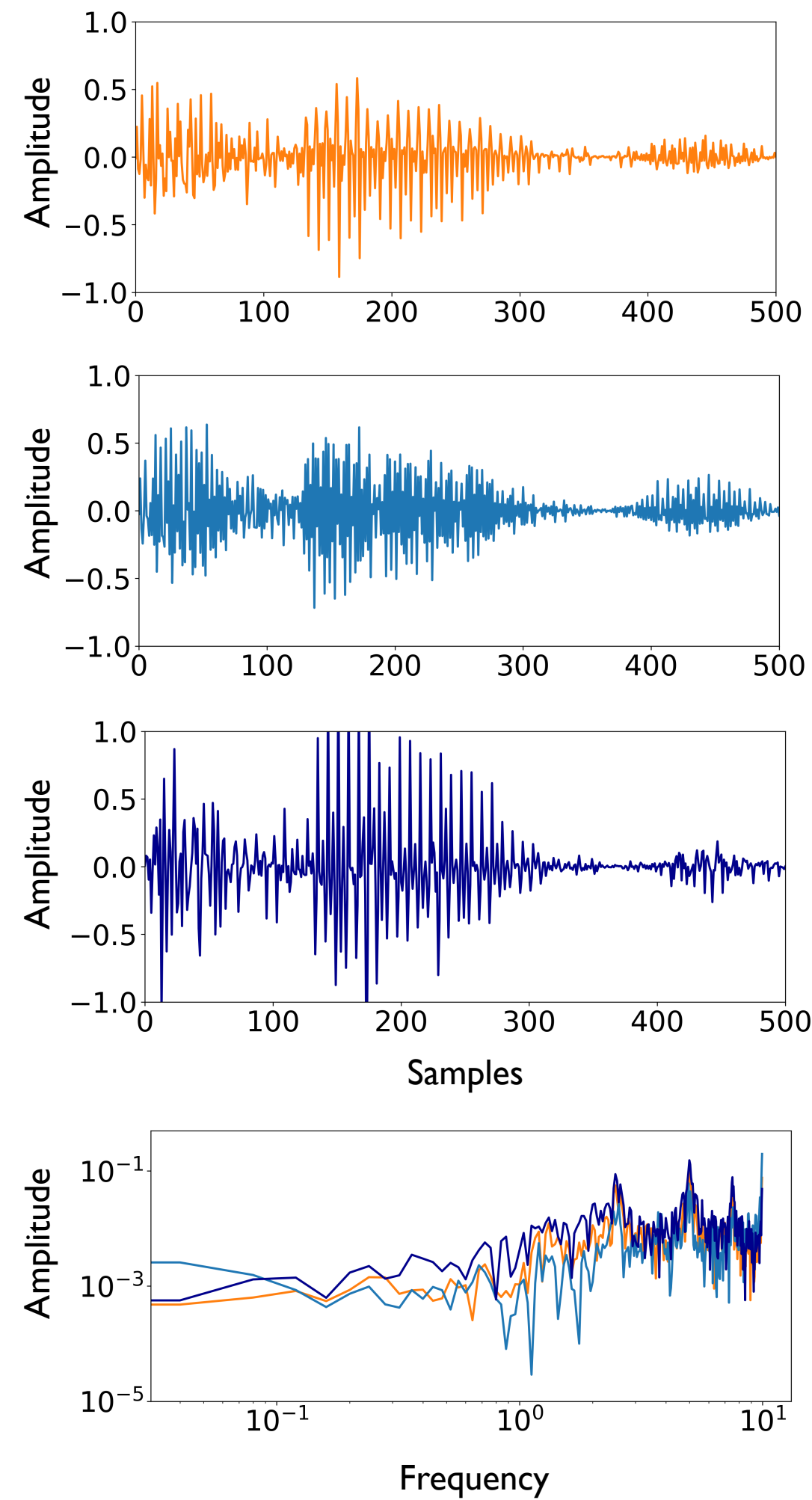
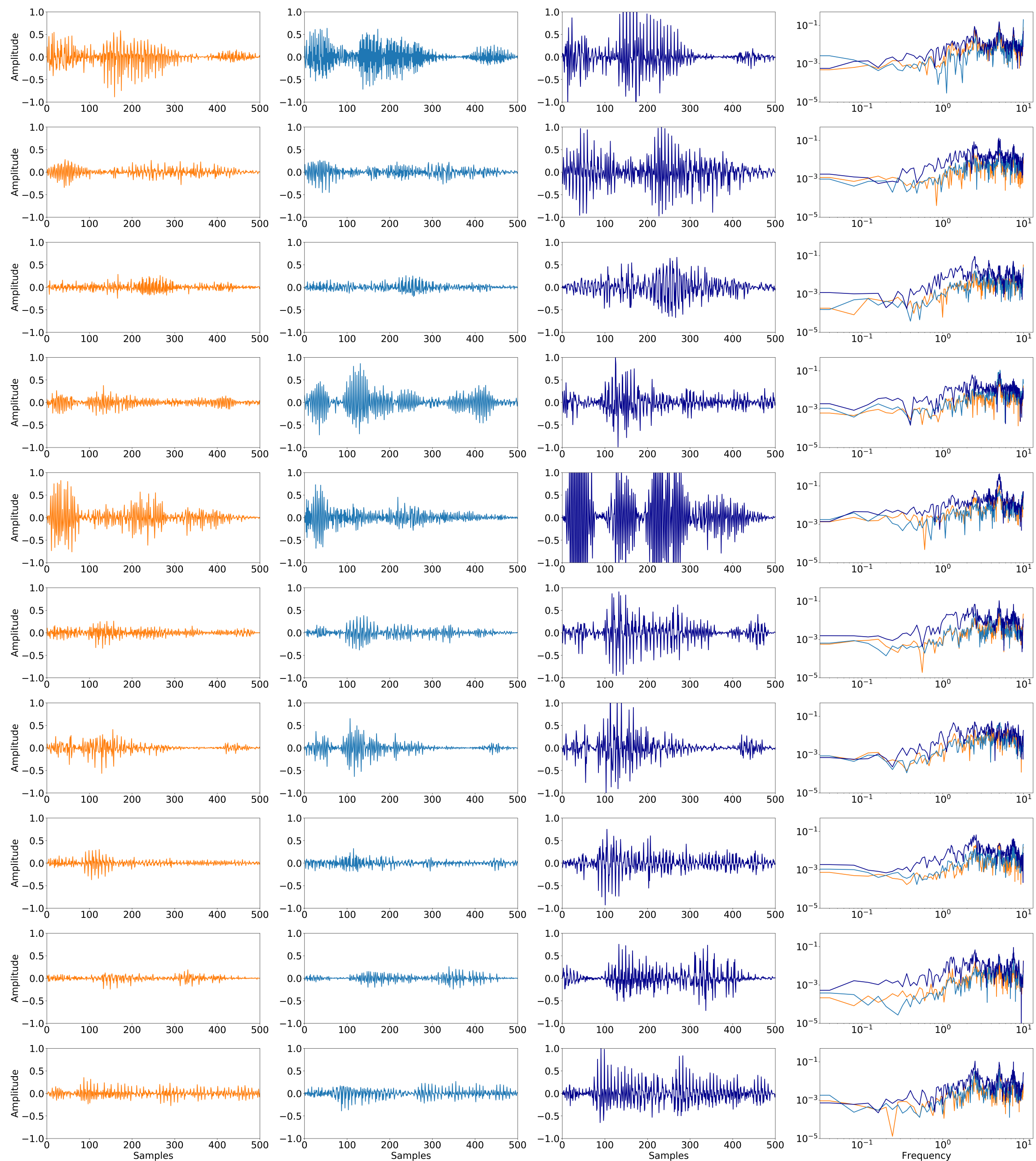
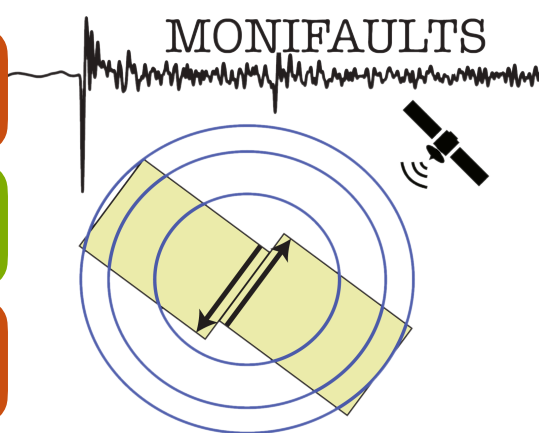
CNN detector

Interpretation

Feature visualisation

Backward optimisation

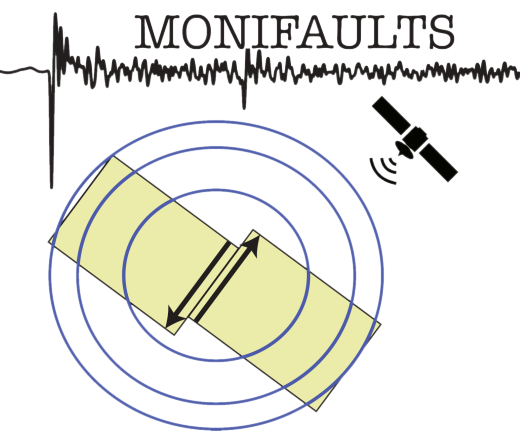
Layer-wise relevance method



E-W component

N-S component

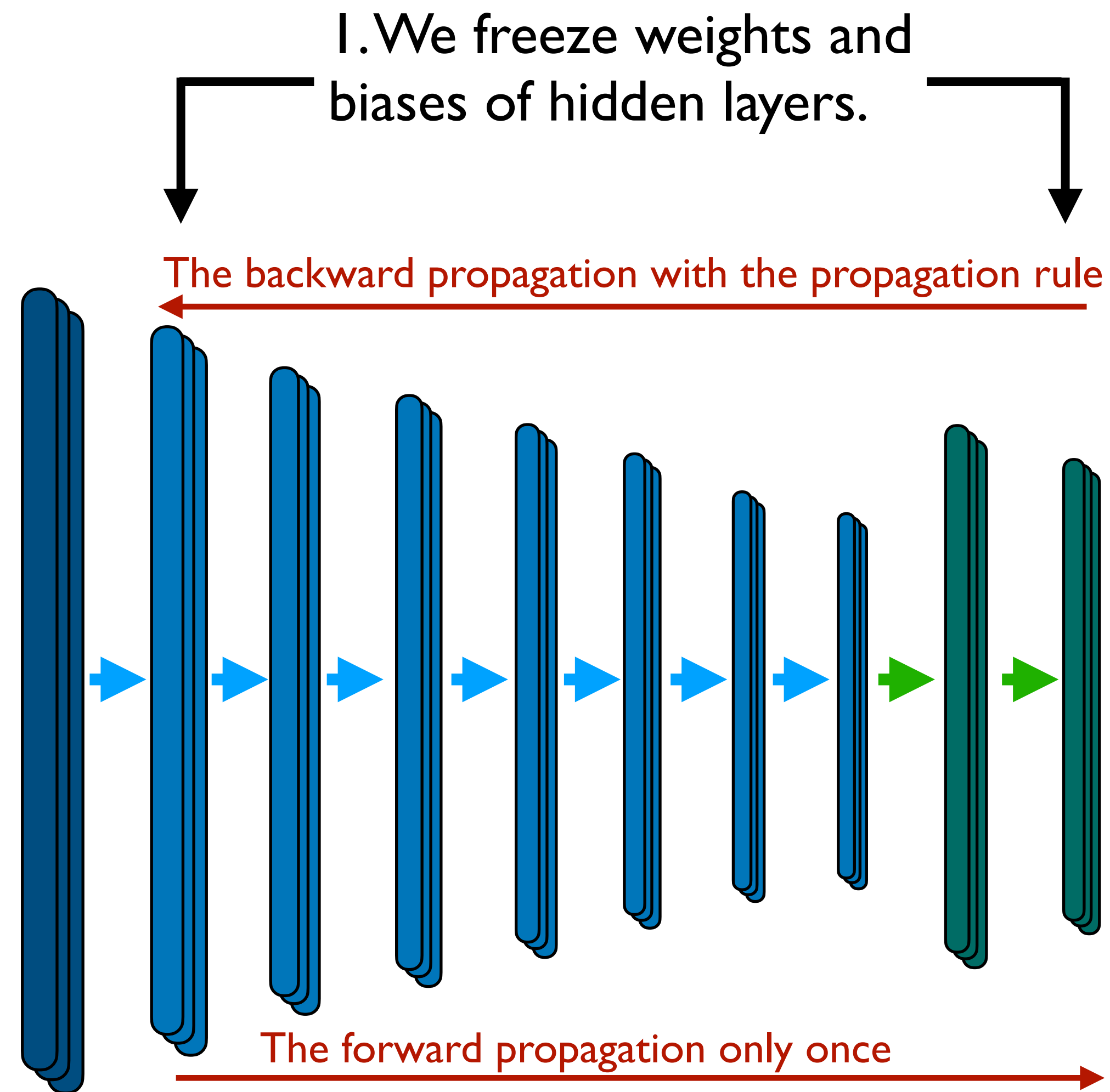
Z component



2. We input real earthquake sample.

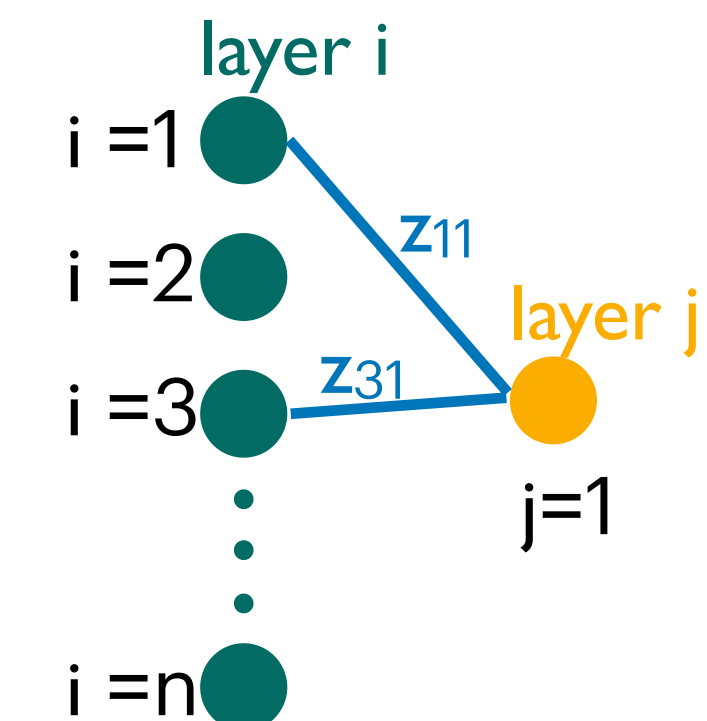
3. Using the frozen weight and biases we obtain the network output by the forward propagation.

4. We calculate the relevance R from the previous layer using the relevance propagation rule called the LRP- β .



The propagation rule LRP- β

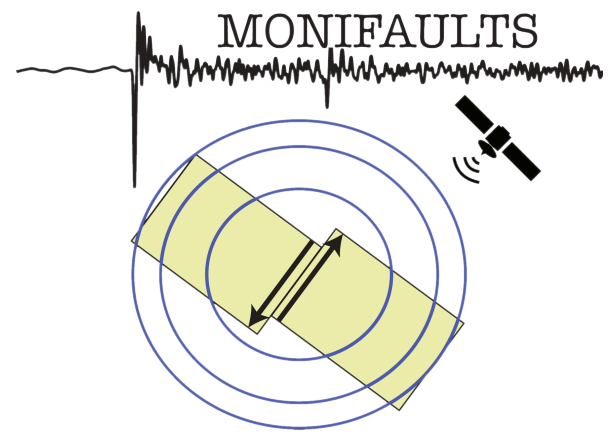
$$R_{l,l+1}^{i \rightarrow j} = \left((1 + \beta) \frac{z_{ij}^+}{z_j^+} - \beta \frac{z_{ij}^-}{z_j^-} \right) R_{l+1}^j$$



$\beta=0$ - we propagate only positive relevance

$\beta=1$ - we propagate only negative relevance

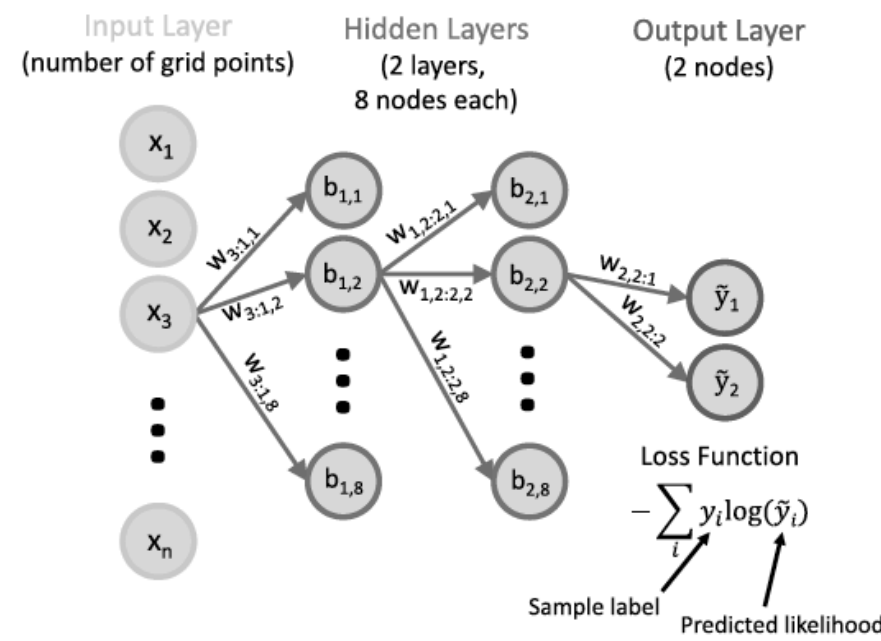
5. We propagate the relevance from the hidden layers up to the input layer.



Basics of neural networks, deep learning models

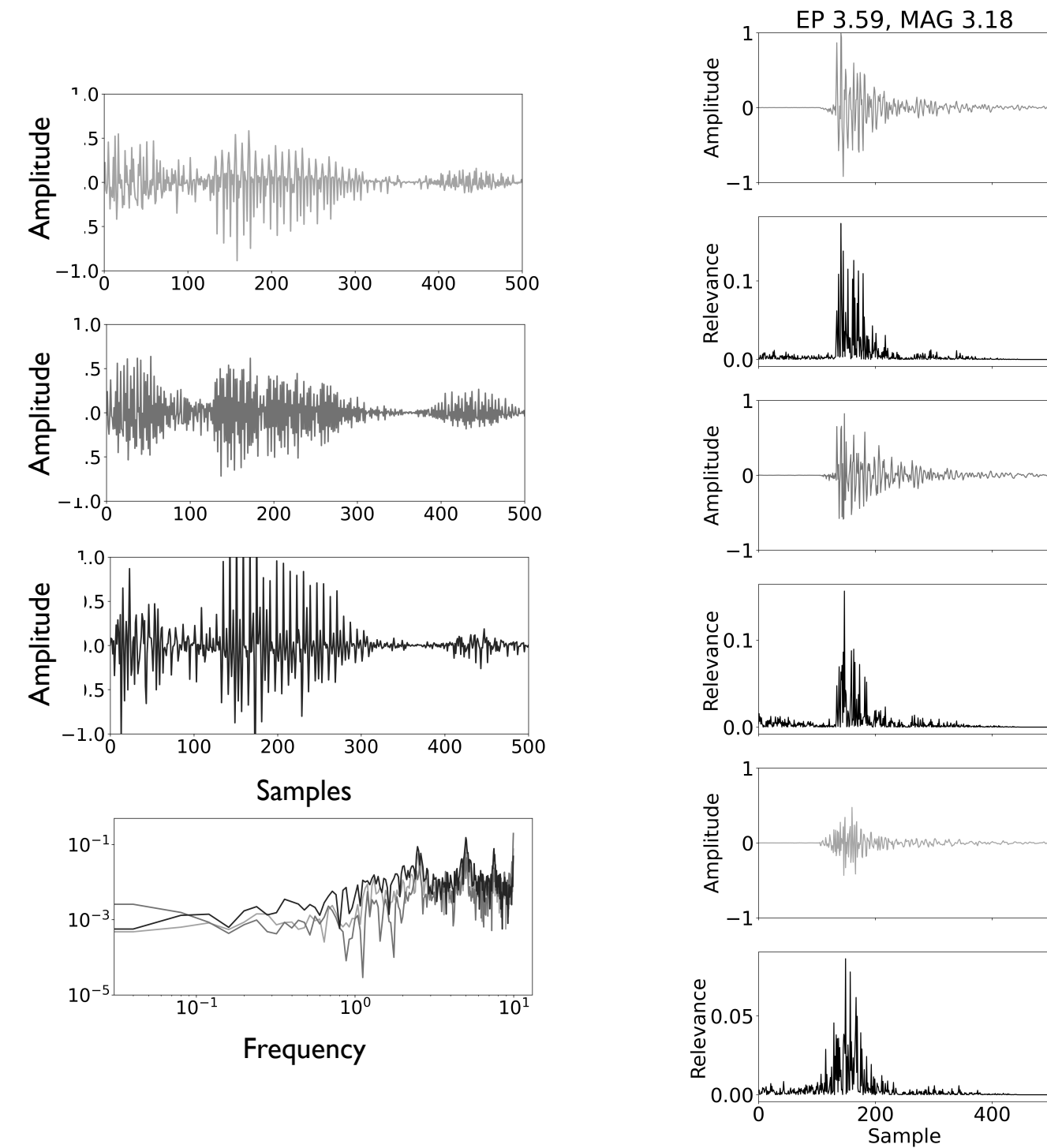
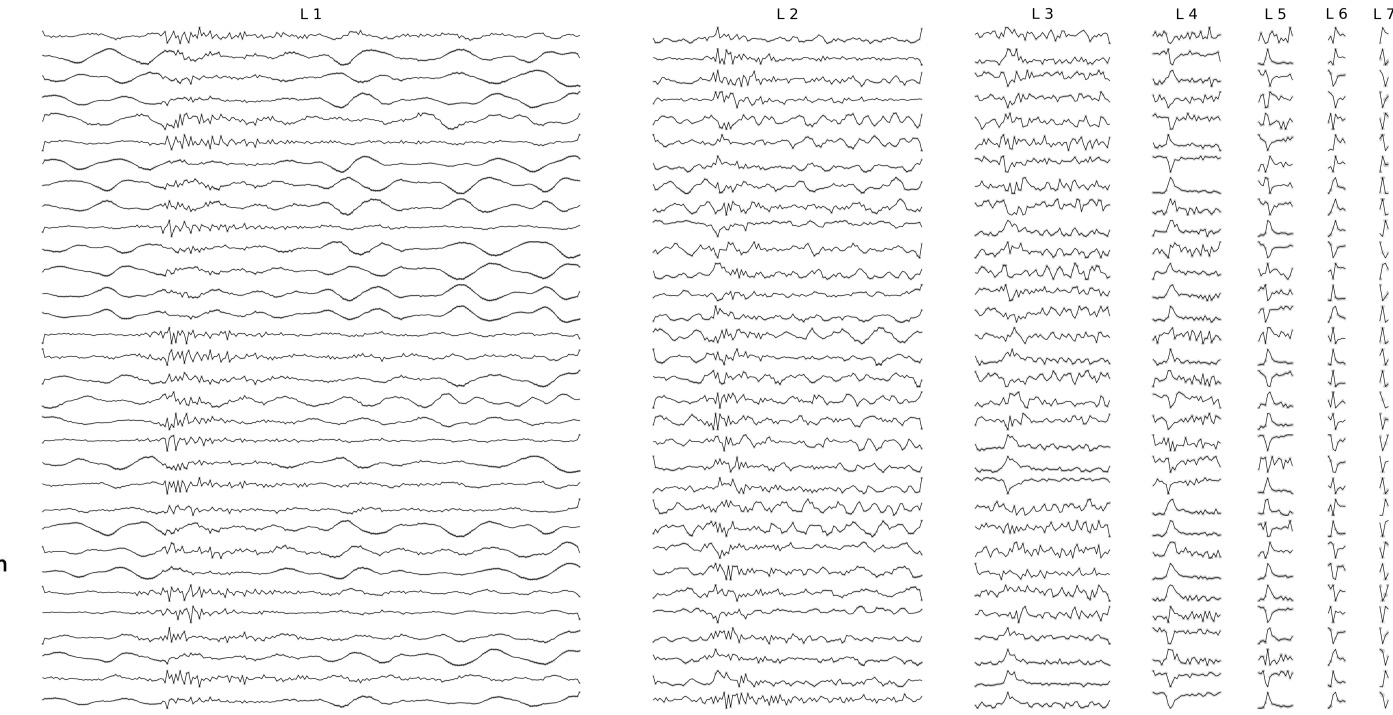
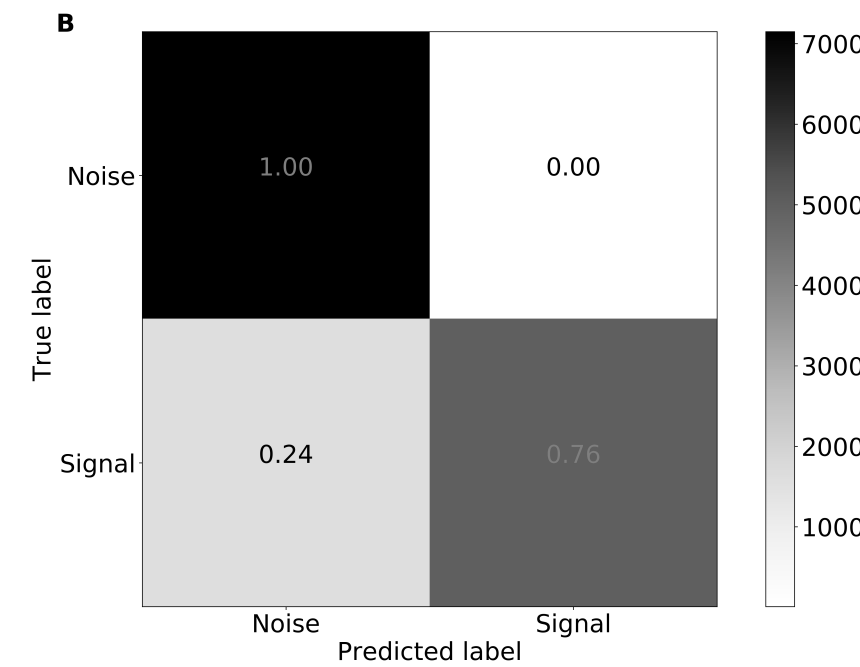
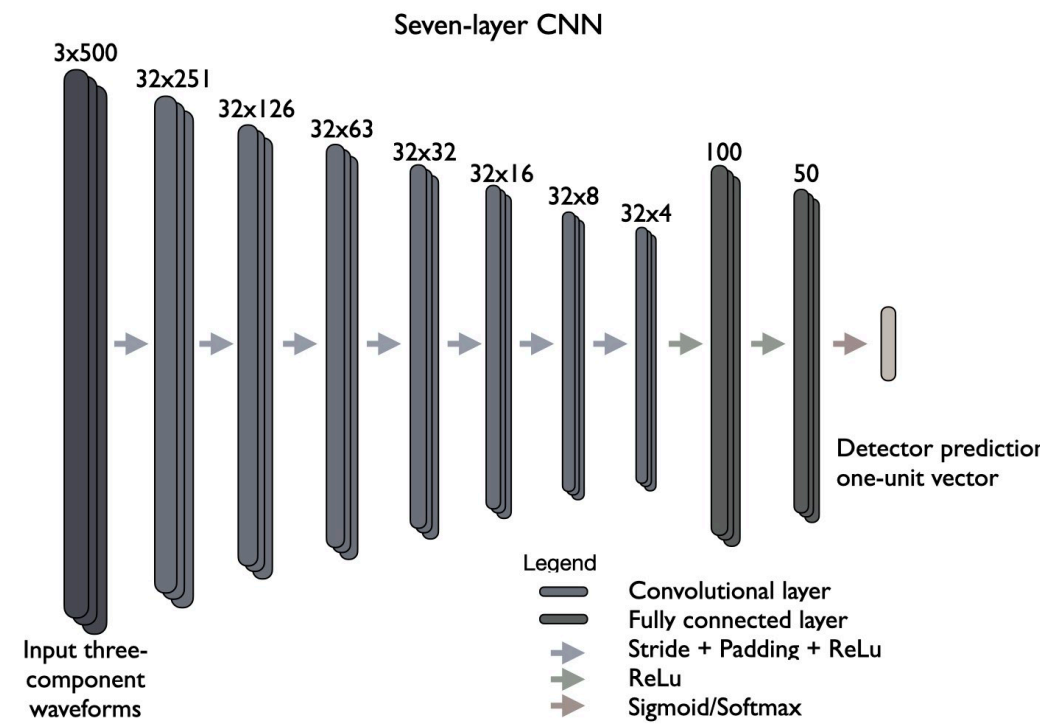
Developing CNN detector

What does interpretation stand for in DL?

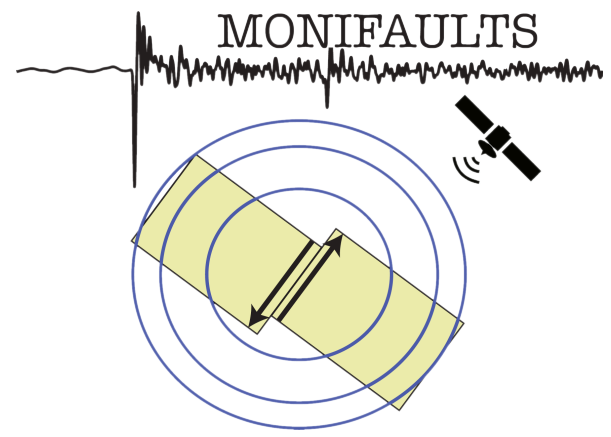


- 1 Training data
- 2 Training process
- 2 Modelling approach
- 3 NN architecture

Majstorović et al., 2021, JGR



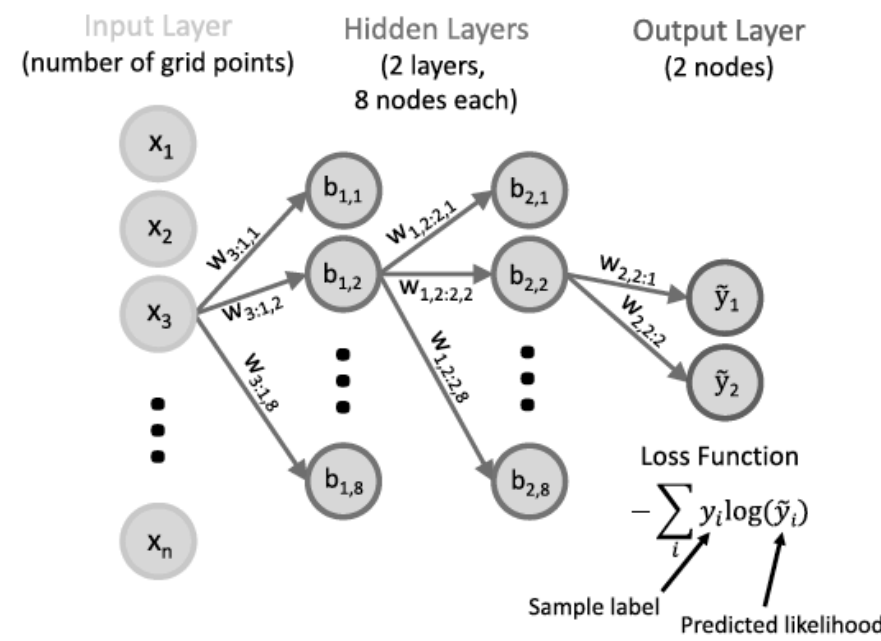
Take away message: there are endless options to explore data with the interpretation methods.



Basics of neural networks, deep learning models

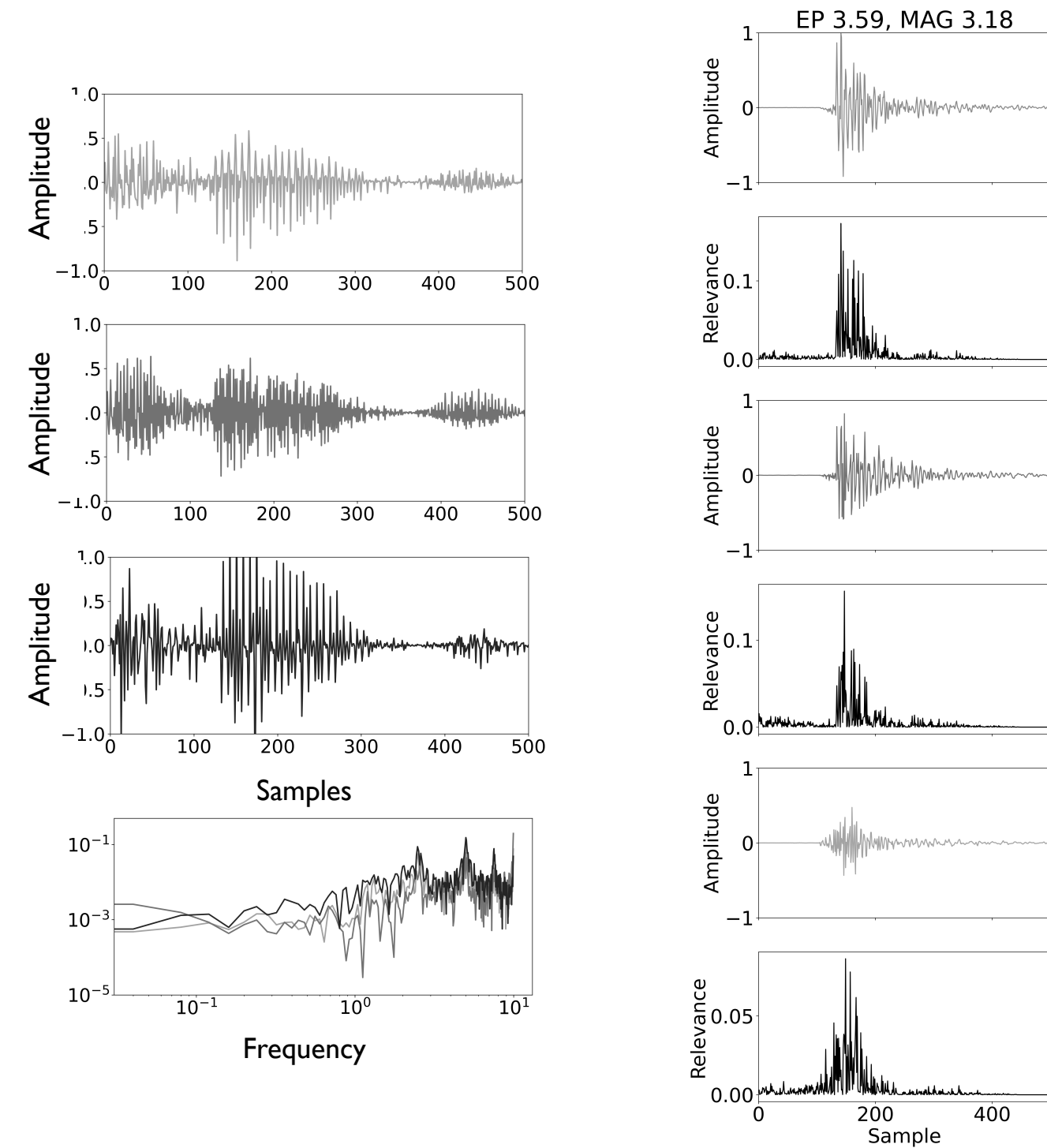
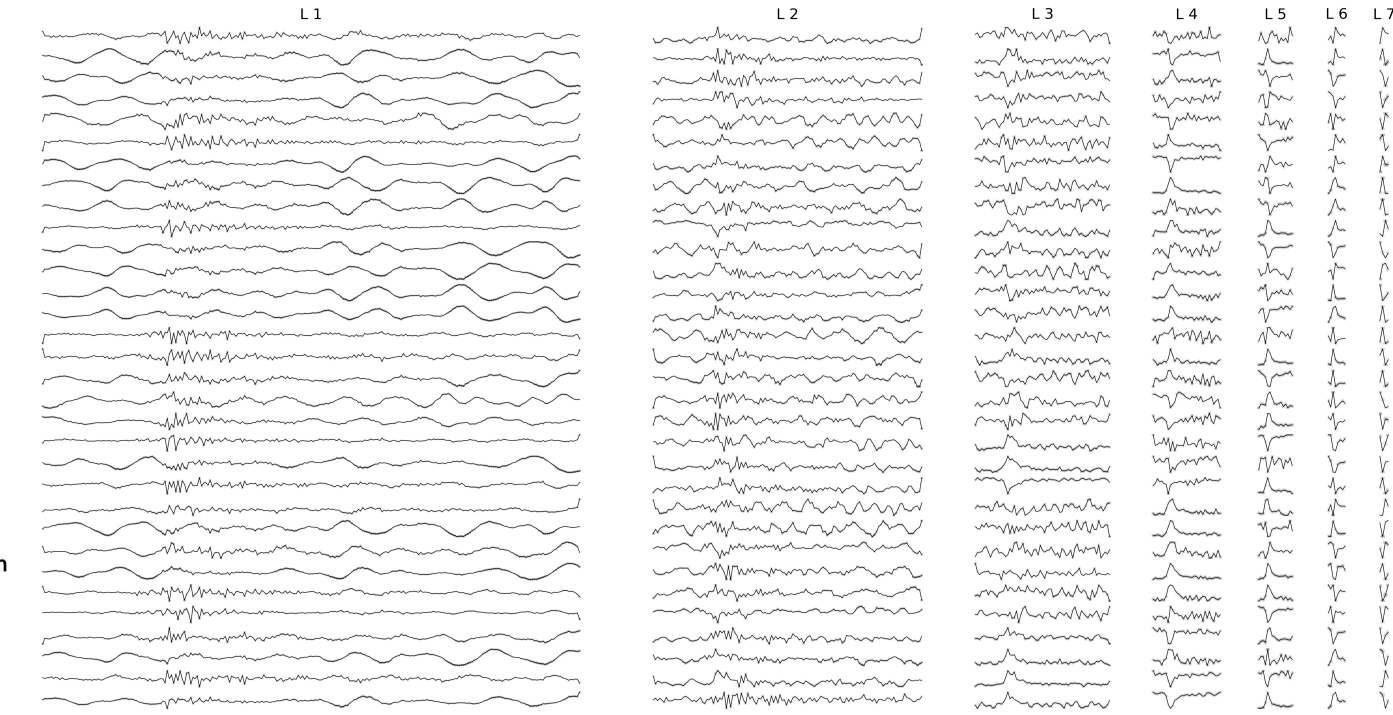
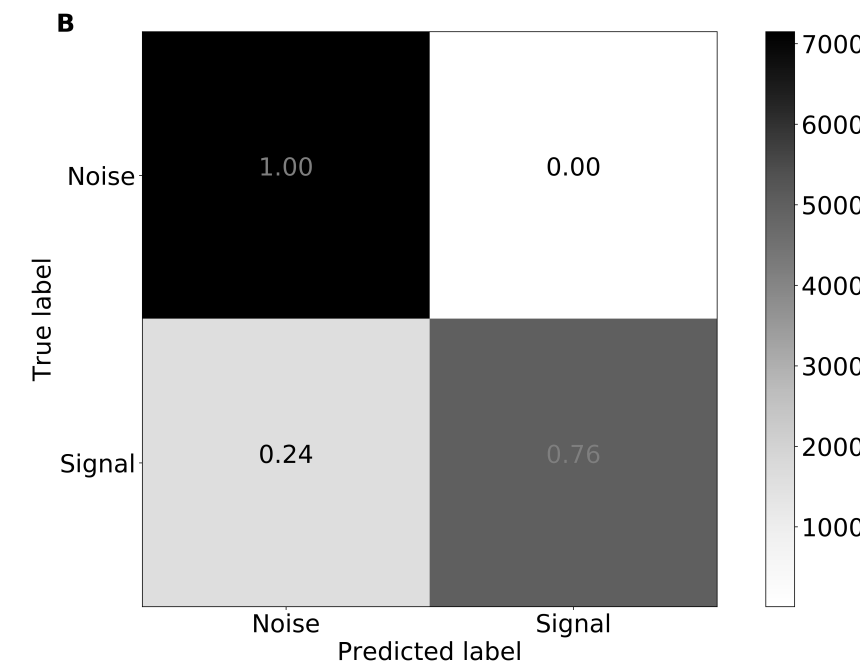
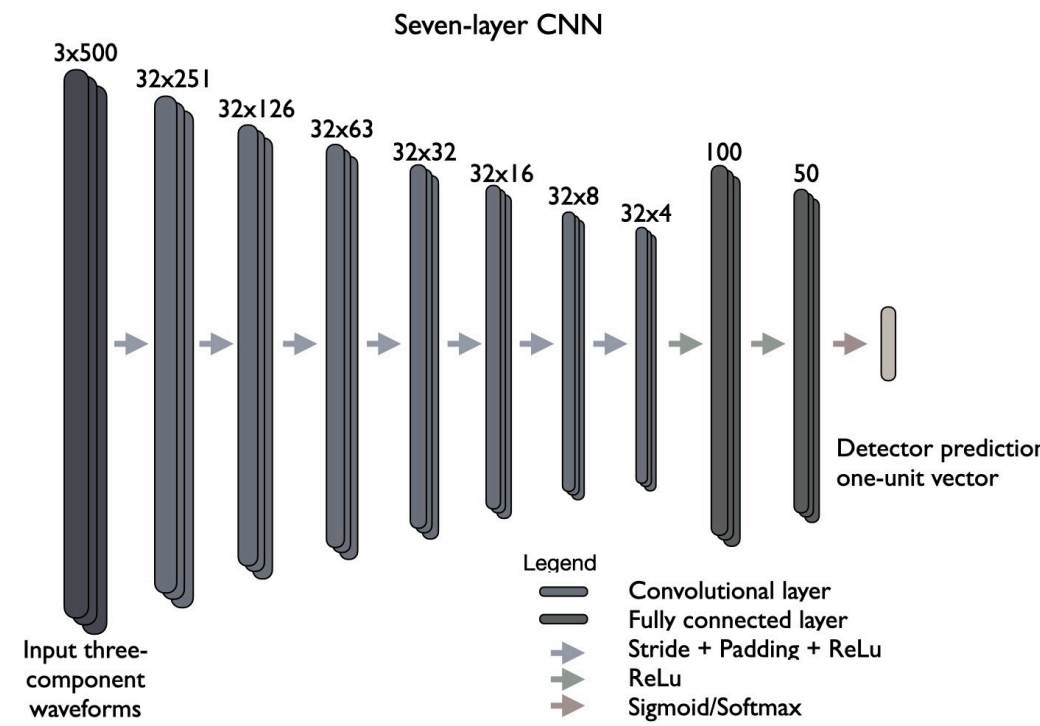
Developing CNN detector

What does interpretation stand for in DL?



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Majstorović et al., 2021, JGR



Take away message: there are endless options to explore data with the interpretation methods.

Thank you for your attention!