





EPOS-GNSS - Processing GNSS data with gamit/globk

Rencontres RESIF

November 18th 2021

Gaël Janex, Anne Socquet, Andrea Walpersdorf

...and previously Aline Déprez, Alizia Tarayoun, Nathalie Cotte, Mary Grace Bato



EPOS

Goal : answering some of the most pressing societal questions concerning geo-hazards and those geodynamic phenomena relevant to the environment and human welfare.

The European Plate Observing System is a multidisciplinary, distributed research infrastructure that facilitates the integrated use of data, data products, and facilities from the solid Earth science community in Europe.

25 COUNTRIES

Austria, Belgium, Bulgaria, Czech Republic, Denmark, Finland, France, Germany, Grecee, Hungary, Iceland, Ireland, Italy, The Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland, Turkey, United Kingdom

5 INTERNATIONAL ORGANIZATIONS Orfeus, EMSC, EUREF, INTERMAGNET, EuroGeoSurveys 256 NATIONAL RESEARCH INFRASTRUCTURES 4939 SEISMIC STATIONS 2272 GPS RECEIVERS 464 TB SEISMIC DATA 118 LABORATORIES 828 INSTRUMENTS Several PetaBytes of solid Earth Science data will be available Several thousands of users expected to access the infrastructure

EPOS ensures the **long-term access** to solid Earth science data and services.

EPOS-GNSS

EPOS-GNSS is one of the 9 EPOS Thematic Core Service (TCS)

The mission of the GNSS TCS is to provide access to GNSS data, metadata, products, and software in support of the Solid Earth Sciences.

To achieve this goal, EPOS-GNSS:

- coordinates the archiving and distribution of relevant GNSS data, metadata and data products
- promotes best practice for GNSS station operation, data quality control and data management
- maintains and distributes open source software for GNSS data, metadata and product discoverability

14 services (Data, Data Products, Software and Services) 3 community portals :



Data : gnssdata-epos.oca.eu



Products : gnssproducts.epos.ubi.pt



GNSS processing within EPOS-GNSS

UGA / CNRS deliverables :

- Double-difference processing (GAMIT/GLOBK, Herring et al., 2015)
 - Time series for EPOS stations
 - Automatic d+2 and d+25 processing
 - Velocities derived from time series

INGV deliverables :

- PPP (Precise Point Positioning) processing (GIPSY)
 - Time series for EPOS stations
 - Velocities derived from time series

GAMIIT/GLOBK

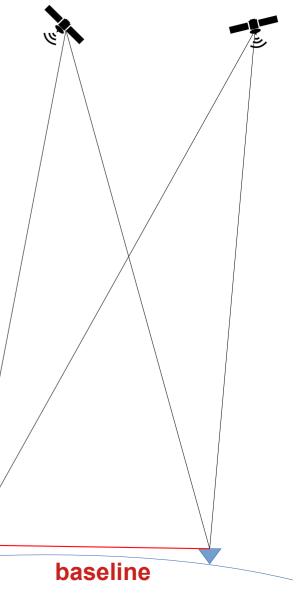
Why double-difference ?



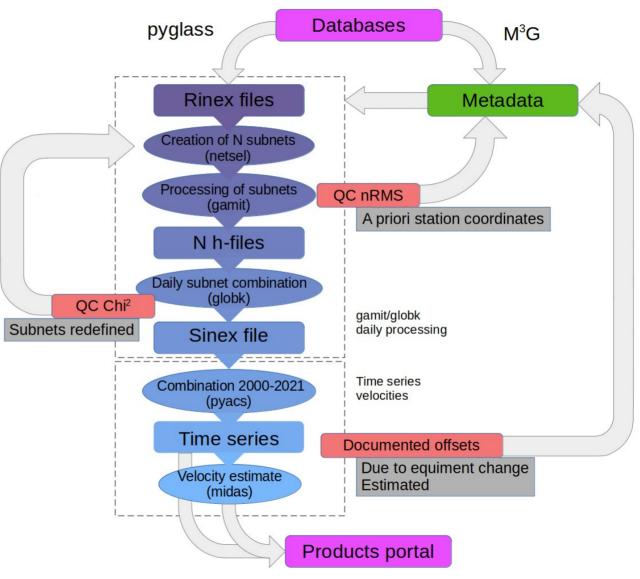
- Takes out satellite and receiver clock errors from calculations
- Reduces the effect of orbit errors
- Reduces the effect of wave propagation unknowns in the atmosphere



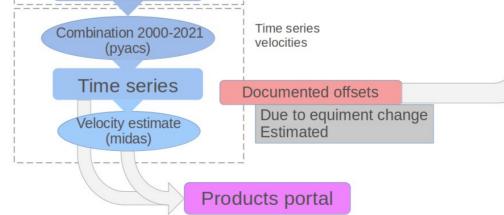
- Since we calculate baselines (distance between each receiver pair), computation costs rise geometrically with number of processed stations
 The dataset is split into subnetworks
 Need to combine subnetwork results together, and reference using IGS stations
- Need to reprocess whole data when new stations (with old data) are added



gamit/globk processing flow



gamit subnetwork processing Databases pyglass M³G **Rinex files** Metadata Creation of N subnets (netsel) Processing of subnets QC nRMS (gamit) A priori station coordinates N h-files Daily subnet combination (globk) QC Chi² gamit/globk Subnets redefined daily processing Sinex file Time series Combination 2000-2021 velocities

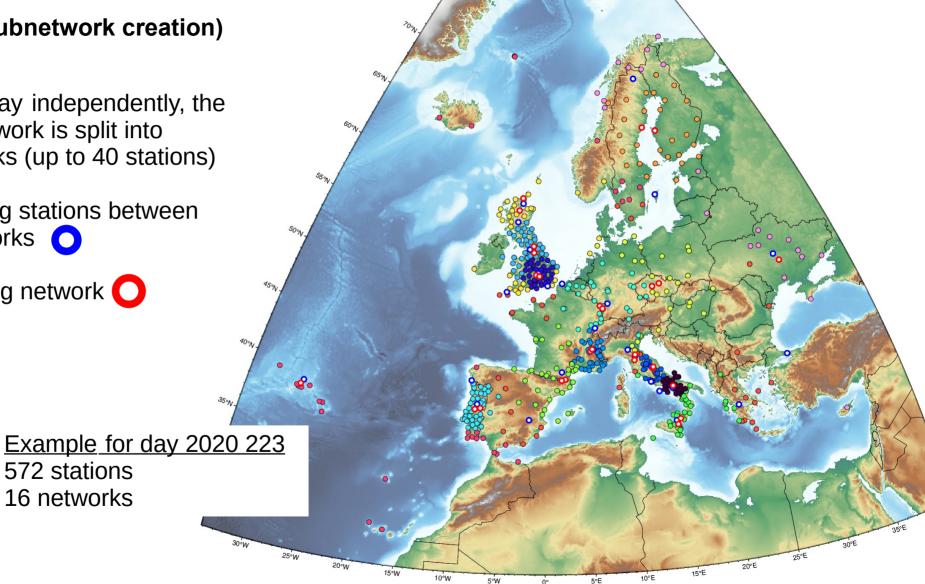


netsel (subnetwork creation)

For each day independently, the station network is split into subnetworks (up to 40 stations)

Overlapping stations between local networks

1 large tying network 🔘



gamit subnetwork processing Databases pyglass M³G **Rinex files** Metadata Creation of N subnets (netsel) Processing of subnets QC nRMS (gamit) A priori station coordinates N h-files Daily subnet combination (globk) QC Chi² gamit/globk Subnets redefined daily processing Sinex file Time series Combination 2000-2021 velocities (pyacs) Time series Documented offsets Due to equiment change Velocity estimate Estimated (midas)

Products portal

Large number of small compute jobs :

Period	gamit subnetwork processing (~ 30 min runtime)	globk daily combinations (~ 1 min runtime)
1 day	1 per subnet : 16-18 currently	1
1 year	~ 6000	365
2000-2021	~ 80000	~ 8000

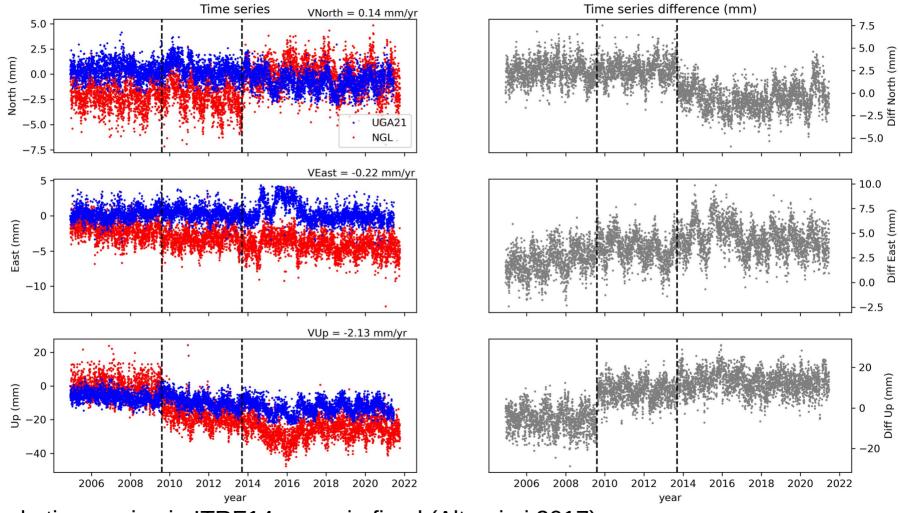
Use of the UGA mutualized high-performance computing platform (ciment)

- Cigri compute grid job submission (best effort mode)
- Input data and results go through iRODS distributed data storage
- Technical IT support provided by the Gricad team.



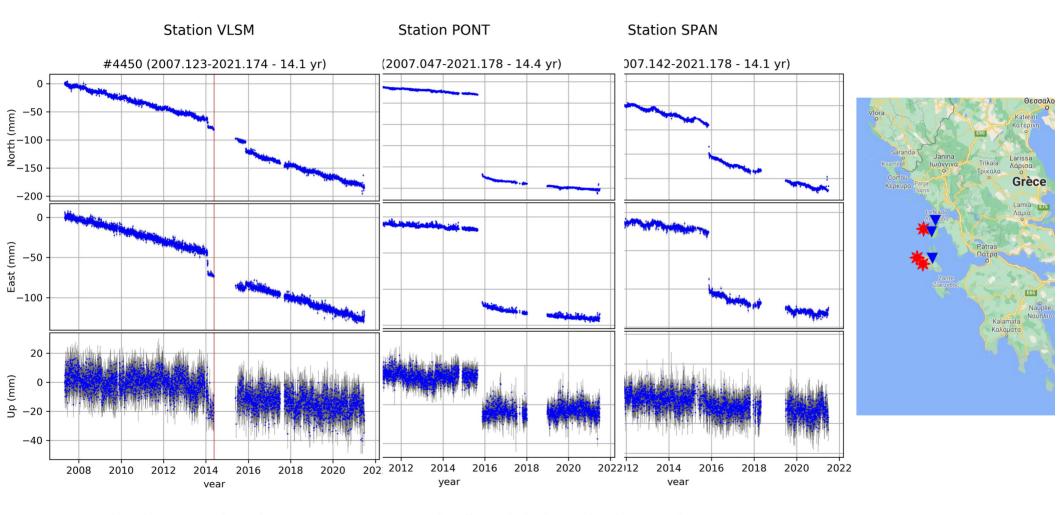


Example time series : ENTZ, gamit processing compared to NGL PPP processing



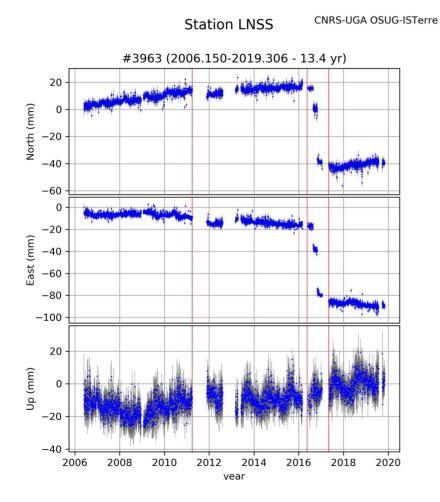
Example time series in ITRF14, eurasia fixed (Altamimi 2017)

Example time series with post-seismic (2014-2015, western Greece)



Example time series in ITRF14, eurasia fixed (Altamimi 2017)

Example time series with post-seismic (L'Aquila, 2016, Italy)





Example time series in ITRF14, eurasia fixed (Altamimi 2017)

Horizontal velocities produced from time series using MIDAS

- MIDAS : Blewitt et al., 2016
- Input data : time series
- Velocity is the most frequent 1-year position shift (sliding window)
- Robust : low sensitivity to outliers, steps, seasonal component.
- Fast (a few minutes for this data set)

615 velocities calculated :

- 576 showed here
- 39 not showed (high errors)

30°E

20°E

10°E

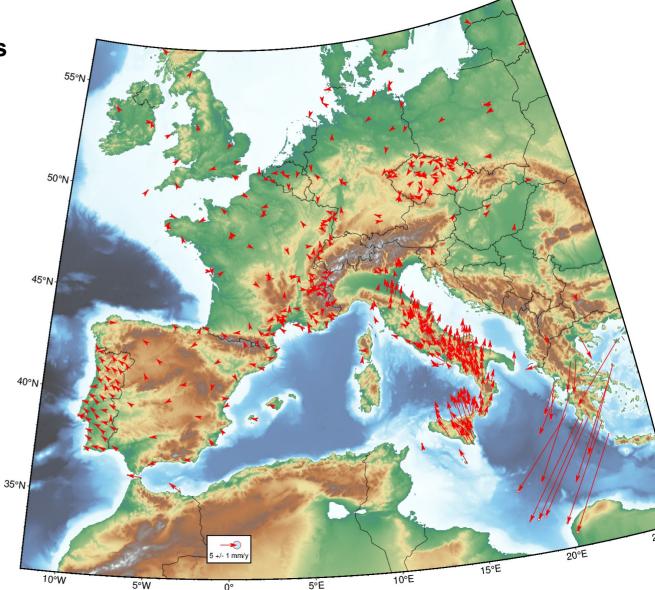
5 +/- 1 mm/

10°W

20°W

Horizontal velocities produced from time series using MIDAS

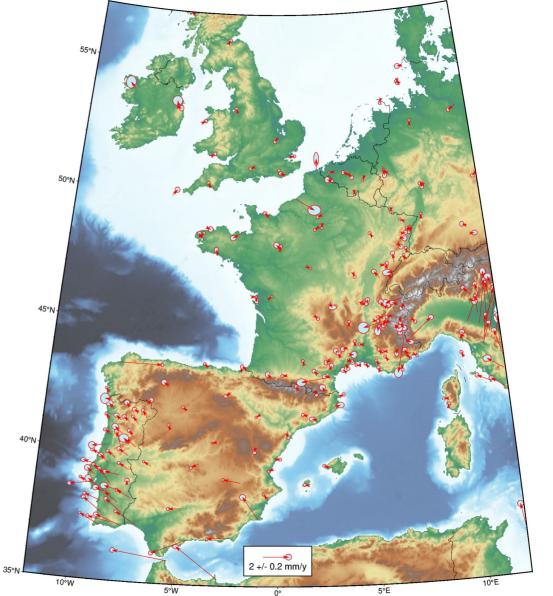
Focus on central Europe



Reference : Eurasia fixed (Altamimi 2017)

Horizontal velocities produced from time series using MIDAS

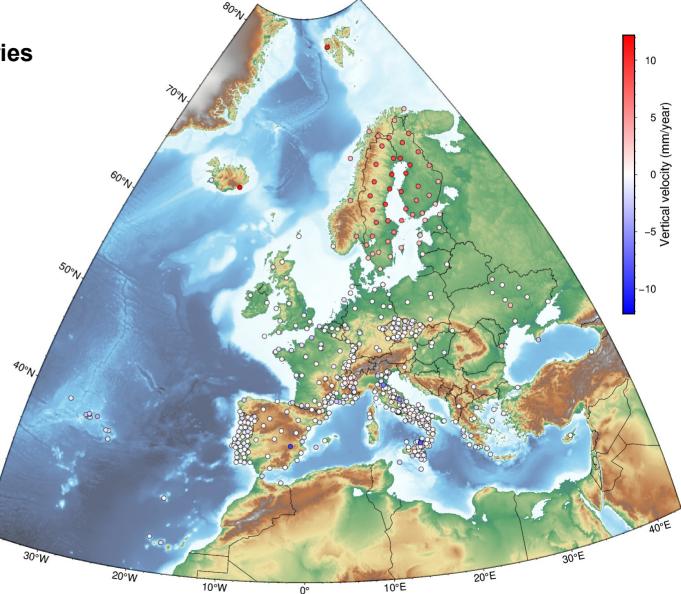
Focus on « stable » western Europe Velocity and errors scaled up for plot

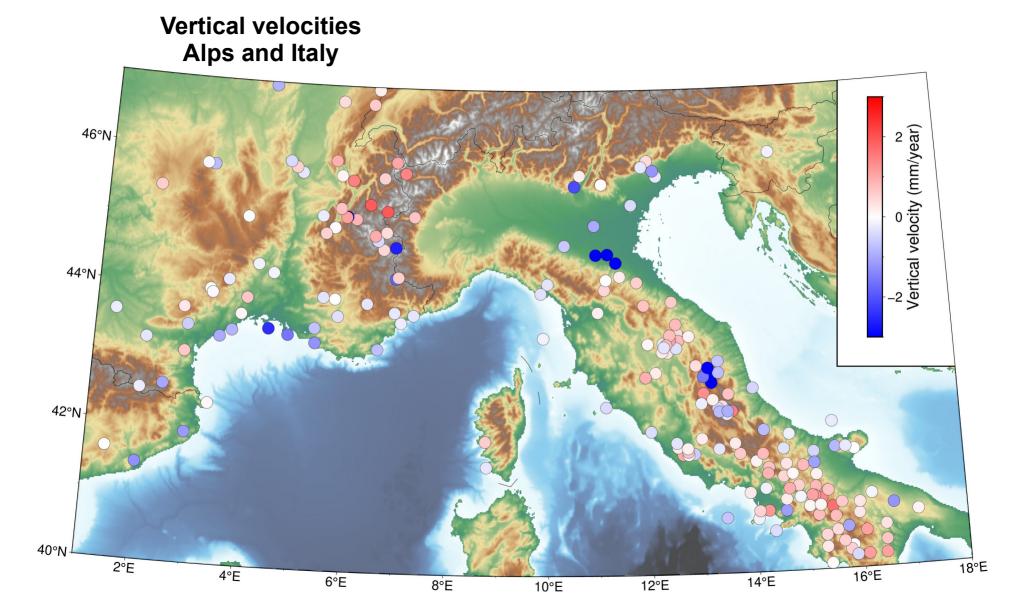


Reference : Eurasia fixed (Altamimi 2017)

Vertical velocities produced from time series using MIDAS

30°N



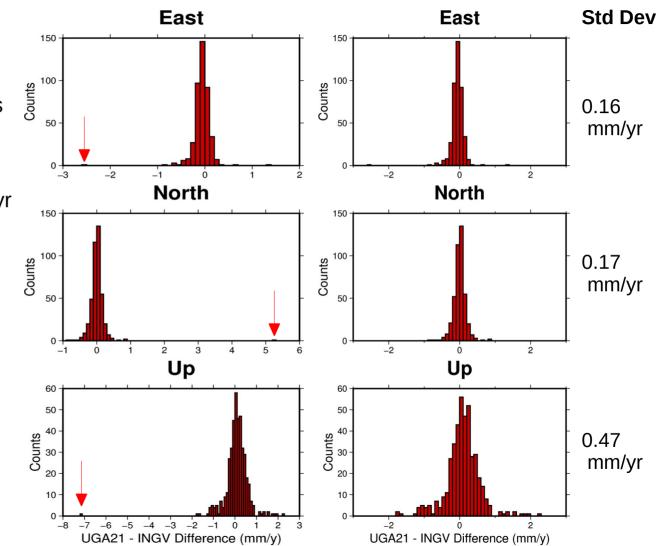


Comparison of velocities : our DD solution vs INGV PPP solution

INGV produces a PPP solution (Gipsy) Velocities are also estimated with Midas

Very good match for most of the 427 stations compared :

- 2 stations with horizontal diff > 1mm/yr
- 2 stations with vertical diff > 2mm/yr



Ongoing / future work

 Valorization through RESIF-RENAG web site, and integration in RENAG combined solution



Séries Temporelles Opérationnelles GNSS RENAG

Solution opérationnelle pour les stations du réseau RENAG (solution automatique non validée scientifiquement).

Le traitement en bref: Le calcul commence en 2000. Le traitement en double différence est effectué avec le logiciel GAMIT (Herring et al., 2010), la mise en référence (ITRF08) et le post-traitement automatique avec le logiciel PYACS (J.-M. Nocquet, Geoazur).

Visualisations: 1/ Raw (sans post-traitement), 2/ Detrended (tendance soustraite), 3/ Offsets removed (offsets dus aux changements de matériels et tendance soustraits).

Traitement automatique opérationnel par le centre de donnée RENAG de Geoazur



Ongoing / future work

 Valorization through RESIF-RENAG web site, and integration in RENAG combined solution

 Automate the times series analysis for offset calculations, using trajectory models tools developped at ISTerre in recent years.

